LSI LOGIC

CW33000 MIPS
Embedded Processor
User’s Manual

A CoreWare™ Product
CW33000 MIPS Embedded Processor User’s Manual

A CoreWare™ Product
Second Edition

This document contains data derived from functional simulations and performance estimates. LSI Logic has not verified either the functional descriptions, or the electrical and mechanical specifications using production parts.

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This book is the primary reference and user's manual for the CW33000 MIPS Embedded Processor building block. It contains a functional description and physical and electrical specifications for the CW33000. Note that the LR33000 Self-Embedding™ Processor User's Manual is a required companion document for this manual; refer to the Related Publications section of this preface for information on how to acquire additional copies of that manual.

**Audience**

This book assumes that you have some familiarity with microprocessors and related support devices. The people who benefit from this book are:

- Engineers and managers who are evaluating the CW33000 building block for possible use in a system design
- Engineers who are designing the building block into a system-on-a-chip

**Organization**

This book has the following chapters:

- Chapter 1, *Introduction*, provides an overview of the CW33000 building block and the CoreWare program.
- Chapter 3, *Signal Definitions*, describes the signals that comprise the CW33000’s bit-level interface to other devices.
- Chapter 4, *Direct CPU Data Bus Interface*, describes in detail the Direct CPU Data Bus Interface, including functional waveforms.
- Chapter 5, *I/O Interface Operation*, discusses and illustrates the CW33000 I/O interface.
- Chapter 6, *AC Specifications*, provides both the AC timing and loading information for the CW33000 megacell.
Related Publications

- LR33000 Self-Embedding Processor User’s Manual, Order Number J14001.A
- LR3000 and LR3000A MIPS RISC Microprocessor User’s Manual, Order Number J14000.A
- CW64500 Central Processing Unit User’s Manual, Order Number C14003
- CFY3900A SCSI Controller User’s Manual, Order Number C14004

Conventions Used in this Manual

The following signal naming conventions are used throughout this manual:

Signal names for active HIGH signals end in P (positive) and signal names for active LOW signals end in N (negative).

Any signal with an overbar over its name is active LOW.

Hexadecimal numbers are indicated by the prefix “0x” before the number—for example, 0x32CF.

The first time a word or phrase is defined in this manual, it is italicized.
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Chapter 1
Introduction

This document describes the LSI Logic CW33000 MIPS Embedded Processor building block. This building block, derived from LSI Logic's LR33000 Self-Embedding™ Processor standard part, also implements the MIPS Reduced Instruction Set Computer (RISC) architecture and executes the MIPS-1 instruction set. The CW33000 is part of LSI Logic's CoreWare™ library of leading-edge microprocessors, floating-point processors, and peripheral functions. Designers can combine the elements from this library with other LSI Logic library elements to implement highly integrated systems in silicon for a wide variety of applications.

This chapter provides an overview of LSI Logic's CoreWare program and the CoreWare library. Then it introduces the CW33000. Finally, it discusses the issue of CW33000 compatibility with the R2000 and R3000 microprocessors. The sections in Chapter 1 are:

- CoreWare Program
- CW33000 Overview
- Compatibility with the R2000 and R3000 Microprocessors

1.1 CoreWare Program

The CoreWare program offers a new approach to system design. Through the CoreWare program, LSI Logic gives customers the ability to combine leading-edge microprocessors, floating-point processors, and peripheral functions on a single chip to create products uniquely suited to the customer's applications. The approach—which combines high-performance building blocks, sophisticated design software, and expert support—provides unparalleled design flexibility and allows designers to create high-quality, leading-edge products for a wide range of markets.
### CoreWare Building Blocks

The CoreWare building blocks include elements based on the LSI Logic high-performance standard products as well as other, industry-standard products. These standard products are leading-edge implementations of RISC microprocessors, floating-point processors, and peripherals. The CoreWare building blocks, ranging from an embedded MIPS processor and a 64-bit floating-point processor to a SPARC SBus interface and a SCSI controller, are fully supported library elements for use in the LSI Logic hardware development environment. Note that the building blocks include simulation models with timing information, so designers can accurately simulate device performance and trade off various implementation options.

### Design Environment

LSI Logic's Modular Design Environment® (MDE®) design and analysis tools and the new C-MDE™ (concurrent MDE) design system provide a complete framework for device and system development and simulation. The MDE toolset and LSI Logic's advanced ASIC technologies consistently produce Right-First-Time™ silicon. The C-MDE system puts even more power in the hands of the designer by providing enhanced MDE capabilities in a concurrent design environment.

### Expert Support

LSI Logic's in-house experts support the CoreWare program with high-level design and market experience in a wide variety of application areas. They provide design support from system architecture definition through chip layout and test vector generation. They help determine how much functionality to integrate on a single chip, trading off functionality versus cost to find the most cost-effective solution. When the trade-offs are complete, the designer and LSI Logic's applications engineers implement and test the design using MDE or C-MDE and the CoreWare building blocks.

### CW33000 Overview

This section introduces the CW33000. First it discusses the architecture and general features of the building block; then it briefly discusses the CPU.
registers, the instruction set, the system control coprocessor (CP0), and operating modes.

Architecture and General Features

The CW33000 building block design is based on the LSI Logic LR33000 Self-Embedding Processor, a standard product. The LR33000 is a high-performance, single-chip microprocessor optimized for embedded control applications. It includes a MIPS-compatible CPU with on-chip instruction and data caches, a DRAM Controller, a sophisticated bus interface unit, and three counter/timers. Figure 1.1 shows a block diagram of the LR33000 standard product.

The CW33000 building block is fundamentally the same processor with a few modifications, as shown in Figure 1.2. The differences, which allow application-specific configuration of the processor, concern the instruction and data caches and communication with the CPU. Note that the CW33000 building block is particularly suited for embedded control applications where introducing additional on-chip functionality enhances system performance, reduces the system chip count and board area, and lowers the system cost.
The shared features of and the differences between the CW33000 and the LR33000 are presented next and discussed in more detail in Chapter 2.

**MIPS CPU** – The CW33000 implements the high-performance MIPS-1 architecture found in the LR33000, with these features:

- **Instruction Set Compatibility** – The CW33000 maintains full binary compatibility with the R2000, R3000, and R3000A microprocessors.

- **Efficient Pipelining** – The CPU’s five-stage pipeline design assists in obtaining an execution rate approaching one instruction per cycle. Pipeline stalls and exceptional events are handled precisely and efficiently.

- **Full 32-Bit Operation** – The CW33000 contains thirty-two 32-bit registers. All instructions and addresses are 32 bits wide to support a 4-Gbyte address space.
Enhanced Debug Features – The CW33000 incorporates a hardware breakpoint on program counter and data address registers to ease software debugging, and it includes program trace support logic.

On-Chip Cache Memory – The CW33000 and LR33000 on-chip cache configurations differ. The LR33000 contains an 8-Kbyte instruction cache and a 1-Kbyte data cache. It can access both caches during a single clock cycle, which allows the processor to execute one instruction per cycle when executing instructions out of cache memory. Both caches employ direct address mapping and support bus snooping to maintain cache coherency. The data cache uses a write-through technique to maintain main memory coherency.

The CW33000 building block offers a 4-Kbyte instruction cache and an optional data cache. The CW33000 contains a data cache controller but does not include the 1-Kbyte data cache. The designer may add the data cache SRAMs to a design based on the CW33000 building block, or the designer may choose not to use a data cache at all and utilize the chip area for another purpose.

On-Chip DRAM Control – The CW33000 has an integral DRAM Controller that supports many popular DRAMs. Its features include support for page-mode DRAMS, CAS-before-RAS refresh, and DMA by separate I/O devices.

Bus Interface Unit (BIU) – The CW33000 BIU provides a sophisticated memory interface that connects easily to I/O devices, supports both 8- and 32-bit PROMs, and includes a programmable wait-state generator. The BIU supports optional parity generation and checking. Checking may be suspended on a per-memory-access basis, and the CW33000 provides the parity error output, PERRP, to signal parity errors to external logic.

On-Chip Counter/Timers – The CW33000 includes three counter/timers: two 24-bit general-purpose timers and a 12-bit refresh timer that can support an on-chip or off-chip DRAM Controller.

Direct CPU Data Bus Interface – Although this interface is not included in the LR33000, the CW33000 includes the Direct CPU Data Bus Interface to provide fast, single-cycle data (operand) transfer between the CPU and dedicated SRAM or ROM that is on-chip but not part of the CW33000 building block.
Like the LR33000, the CW33000 CPU provides 32 general-purpose 32-bit registers, a 32-bit program counter, and two 32-bit multiply/divide registers, HI and LO, that hold the results of integer multiply and divide operations. The CPU registers are shown in Figure 1.3 and are discussed in Section 2.1, "Data and Registers." Notice that the figure does not contain a Program Status Word (PSW) register; the functions traditionally provided by a PSW register are instead provided by the Status and Cause registers incorporated within the system control coprocessor (CP0).

The CW33000 executes the same instruction set as the LR33000 standard part. All CW33000 instructions are 32 bits long. As shown in Figure 1.4, instructions have three basic formats: I-type (immediate), J-type (jump), and R-type (register). Instruction decoding is simplified by this approach. The compiler can synthesize more complex and less frequently used operations and addressing modes using sequences of simple RISC-type instructions. The assembler recognizes some CISC-type instructions for programming ease, but translates them into sequences of simple instructions.
The CW33000 instruction set is divided into the following groups:

- **Load/Store** instructions are the only instructions that move data between memory and general registers. These instructions are I-type, because the only addressing mode supported is base register plus a 16-bit, signed immediate offset.

- **Computational** instructions perform arithmetic, logical, and shift operations on values in registers. These instructions are either R-type (both operands and the result are registers) or I-type (one operand is a 16-bit immediate).

- **Jump and Branch** instructions change the control flow of a program. Jumps are always to a paged, absolute address either formed by combining a 26-bit target with four bits of the program counter (J-type format, for subroutine calls), or from the contents of a 32-bit byte address register (R-type, for returns and dispatches). Branches have 16-bit offsets relative to the program counter (I-type).

- **Coprocessor** instructions specify coprocessor operations. Most of these instructions are not implemented by the CW33000. See Section 1.3, “Compatibility with the R2000 and R3000 Microprocessors,” for details.

- **Coprocessor 0** instructions specify operations on the system control coprocessor (CP0) registers to manipulate the exception-handling facilities of the processor.

- **Special** instructions perform a variety of tasks including movement of data between special and general registers, system calls, and breakpoint. These instructions are always R-type.
Table 1.1 lists the instruction set of the CW33000 processor. A more detailed summary is provided in Section 2.2, “Instruction Set Summary.”
**Table 1.1**
**CW33000/LR33000**
**Instruction Summary**

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<td>LB</td>
<td>Load Byte</td>
<td>SRA</td>
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<td>Load Byte Unsigned</td>
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<td>SRLV</td>
<td>Shift Right Logical Variable</td>
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<td>LHU</td>
<td>Load Halfword Unsigned</td>
<td>SRAV</td>
<td>Shift Right Arithmetic Variable</td>
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<td>LWR</td>
<td>Load Word Right</td>
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<td>SB</td>
<td>Store Byte</td>
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<tr>
<td>MTHI</td>
<td>Move To HI</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MFLO</td>
<td>Move From LO</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MTLO</td>
<td>Move To LO</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Jump and Branch Instructions</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>J</td>
<td>Jump</td>
<td></td>
<td></td>
</tr>
<tr>
<td>JAL</td>
<td>Jump And Link</td>
<td></td>
<td></td>
</tr>
<tr>
<td>JR</td>
<td>Jump Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>JALR</td>
<td>Jump And Link Register</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BEQ</td>
<td>Branch on Equal</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BNE</td>
<td>Branch on Not Equal</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BLEZ</td>
<td>Branch on Less than or Equal to Zero</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BGTZ</td>
<td>Branch on Greater Than Zero</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BLTZ</td>
<td>Branch on Less Than Zero</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BGEZ</td>
<td>Branch on Greater than or Equal to Zero</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BLTZAL</td>
<td>Branch on Less Than Zero And Link</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BGEZAL</td>
<td>Branch on Greater than or Equal to Zero And Link</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Special Instructions</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>SYSCALL</td>
<td>System Call</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BREAK</td>
<td>Breakpoint</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Coprocessor Instructions</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BCzT</td>
<td>Branch on Coprocessor z True</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BCzF</td>
<td>Branch on Coprocessor z False</td>
<td></td>
<td></td>
</tr>
<tr>
<td>System Control Coprocessor (CP0) Instructions</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>MTC0</td>
<td>Move To CP0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MFC0</td>
<td>Move From CP0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RFE</td>
<td>Restore From Exception</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
System Control Coprocessor (CP0)  The CW33000 system control coprocessor (CP0) supports exception-handling functions of the CW33000. Figure 1.5 summarizes the register set. Refer to Section 2.3, “Exception Processing,” for descriptions of the exception-processing registers.

<table>
<thead>
<tr>
<th>Figure 1.5</th>
<th>The CP0 Exception-Handling Registers</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Status Register</td>
</tr>
<tr>
<td></td>
<td>Cause Register</td>
</tr>
<tr>
<td>Bad Address (BadA) Register</td>
<td>Exception Program Counter (EPC) Register</td>
</tr>
<tr>
<td>Debug and Cache Invalidate Control (DCIC) Register</td>
<td>Processor Revision ID (PRId) Register</td>
</tr>
<tr>
<td>Breakpoint Program Counter (BPC) Register</td>
<td>Breakpoint Data Address (BDA) Register</td>
</tr>
</tbody>
</table>

Operating Modes  To facilitate the separation of user and supervisory software, the CW33000 has two operating modes: user and kernel. Normally, the processor operates in the user mode until an exception is detected, which forces it into the kernel mode. It remains in the kernel mode until a Restore From Exception (RFE) instruction is executed. Figure 1.6 shows the address space for the two operating modes.

**User Mode** – In user mode, a single, uniform address space (kuseg) of 2 Gbytes is available.

**Kernel Mode** – Four separate segments are defined in kernel mode:

- *kuseg* – References to this 2-Gbyte segment are treated just like user mode references, thus streamlining kernel access to user data.
- *kseg0* – References to this 512-Mbyte segment use cache memory and are hard-mapped to the first 512 Mbytes of memory.
- *kseg1* – References to this 512-Mbyte segment do not use the cache and are hard-mapped into the same 512-Mbyte segment of memory space as *kseg0*.
- *kseg2* – References to this 1-Gbyte segment are not mapped and the cacheability of data and instructions is controlled on a per access basis by the CACHDN signal.
Figure 1.6
CW33000/LR33000
Address Space

Introduction
1.3 Compatibility with the R2000 and R3000 Microprocessors

The CW33000 MIPS Embedded Processor provides instruction set compatibility with the R2000 and R3000A microprocessors. Therefore, software developed for the R2000 and R3000A can be easily ported to systems based on the CW33000, significantly reducing software development time and resource requirements.

However, like the LR33000, the CW33000 does not support external coprocessors and does not implement the R2000/R3000A memory management unit (MMU). In addition, the internal cache memories are managed differently and two hardware breakpoint registers have been added to facilitate software debugging. These differences are further described under “The System Control Coprocessor CP0,” below.

### Coprocessor Support

The CW33000 does not support external coprocessors. To prevent unpredictable results should a coprocessor instruction be decoded, all external coprocessors should be disabled by setting the appropriate coprocessor usability bits in CP0’s Status Register to zero. When the coprocessors are disabled in this way, the detection of a coprocessor instruction causes a Coprocessor Unusable Exception. Table 1.2 lists the unsupported coprocessor instructions.

<table>
<thead>
<tr>
<th>Op</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LWCz</td>
<td>Load Word from Coprocessor</td>
</tr>
<tr>
<td>SWCz</td>
<td>Store Word to Coprocessor</td>
</tr>
<tr>
<td>MTCz</td>
<td>Move To Coprocessor</td>
</tr>
<tr>
<td>MFCz</td>
<td>Move From Coprocessor</td>
</tr>
<tr>
<td>CTCz</td>
<td>Move Control To Coprocessor</td>
</tr>
<tr>
<td>CFCz</td>
<td>Move Control From Coprocessor</td>
</tr>
<tr>
<td>COPz</td>
<td>Coprocessor Operation</td>
</tr>
<tr>
<td>TLBR</td>
<td>Read indexed TLB entry</td>
</tr>
<tr>
<td>TLBWI</td>
<td>Write Indexed TLB entry</td>
</tr>
<tr>
<td>TLBWR</td>
<td>Write Random TLB entry</td>
</tr>
<tr>
<td>TLBP</td>
<td>Probe TLB for matching entry</td>
</tr>
</tbody>
</table>

1. The CW33000 implements this instruction for CP0 when in kernel mode.

The CW33000 provides four coprocessor condition signals that software can test using the Branch on Coprocessor z True and Branch on Coprocessor z False (BCzT and BCzF) instructions. This facility allows software to
directly monitor hardware that is connected to the condition signals. The corresponding coprocessor must be enabled to use the test instruction. See Section 2.2, "Instruction Set Summary," for a description of the BCzT and BCzF instructions and Section 3.4, "Peripheral Interface Signals," for a description of the coprocessor condition signals.

The CW33000 does not implement the R2000/R3000A memory management unit, which includes the Translation Lookaside Buffer (TLB). Consequently, the CW33000 does not implement any of the instructions designed to maintain and use the TLB. If the processor detects a TLB instruction, it causes a Reserved Instruction Exception. Refer to Table 1.2 for a list of the unimplemented instructions. Note that the CW33000 does not implement the TLB registers in CP0: EntryHi, EntryLo, Index, Random, and Context; references to those registers cause a Reserved Instruction Exception.

Although it does not include the TLB registers, the CW33000 implementation of CP0 does include the additional debug and control registers summarized below. Section 2.3, "Exception Processing," contains more information on CP0.

**Debug Registers** – The CW33000 includes program counter and data address breakpoint registers to simplify software debugging. These registers have been incorporated into CP0, and software accesses them using Move from Coprocessor and Move to Coprocessor (MFC0 and MTC0) instructions.

**Debug and Cache Invalidate Control Register** – This register contains the enable and status bits for the CW33000 debug mechanism, as well as the control bits for the Cache Controller's invalidate mechanism. The CW33000 does not implement the R2000/R3000 cache control bits, which are located in the R2000/R3000 Status Register.
Chapter 2
CW33000 and LR33000: Similarities and Differences

This chapter discusses some major aspects of the CW33000 in terms of their similarities and differences with corresponding aspects of the LR33000 standard part. The chapter covers:

- Data and Registers
- Instruction Set Summary
- Exception Processing
- Memory System Architecture
- Cache Operation
- Counter/Timers
- Signal Definitions
- DRAM Controller Operation
- I/O Interface Operation
- Specifications

Note that the order of these topics parallels the chapter organization in the LR33000 Self-Embedding Processor User's Manual, for ease of reference.

2.1 Data and Registers
The CW33000 data formats and addressing scheme, as well as general register configuration, are identical to those in the LR33000; read Chapter 2, "Data and Registers," and Appendix B, "Memory-Mapped Register Summary," in the LR33000 Self-Embedding Processor User’s Manual for complete details. Note that all general registers must be initialized during simulation, whether or not they are used in the simulation.

2.2 Instruction Set Summary
The CW33000 executes the same instruction set as the LR33000. Refer to the LR33000 Self-Embedding Processor User’s Manual Chapter 3, "Instruction Set Summary," Appendix A, "Instruction Set Details," and
2.3 Exception Processing

The CW33000 and the LR33000 handle exceptions identically except for CW33000-based designs that include on-chip memory. Section 4.3 of this manual describes how to handle instruction exceptions that involve the CW33000 Direct CPU Data Bus Interface and user-designed on-chip memory. Otherwise, for general information on exception handling, refer to Chapter 4, “Exception Processing,” in the LR33000 Self-Embedding Processor User’s Manual.

Note that if the CW33000-based design does not include a data cache, then the function of the D (Data Invalidate Enable) bit, bit 13 in the Debug and Cache Invalidate Control Register (described in Chapter 4 of the LR33000 manual), alters slightly. In systems with a data cache, software sets the D bit to one to enable the data cache invalidate mechanism; then, when the software performs a store instruction, the data cache controller invalidates the data cache line at the effective store address. In a system with no data cache, if software sets the bit and tries to perform the store, neither the data cache invalidate nor the store to memory occurs.

2.4 Memory System Architecture

The CW33000 memory system architecture does deviate from that of the LR33000 in these three significant ways:

- The CW33000 offers a 4-Kbyte instruction cache (I-cache), instead of an 8-Kbyte I-cache.
- The 1-Kbyte data cache (D-cache) is optional; the user may choose to disable the D-cache controller and not include the data cache SRAM in a design.
- The user may include an on-chip memory in a design.

The impact of the I-cache and D-cache changes are described in more detail in the next section of this chapter, “Cache Operation.”

Any CW33000-based design that includes an on-chip memory (described in Chapter 4 of this manual) must provide dedicated memory address space for the on-chip memory. Figure 2.1 shows the CW33000 memory map. The user should select the address space location appropriately, depending on whether on-chip memory will be used for user or kernel mode operations. Note that the user should position the on-chip memory address space.
at either the bottom or top of the appropriate address space to leave the maximum amount of contiguous unassigned address space for other uses.

2.5 Cache Operation

As mentioned previously, the CW33000 I-cache and D-cache configurations deviate somewhat from those of the LR33000; these differences are discussed below. Fundamental I-cache operation is, however, as described in Chapter 6 of the LR33000 Self-Embedding Processor User's Manual; Chapter 6 also contains a description of the D-cache operation. In addition to the fundamental cache operation information presented in Chapter 6, please note the following information concerning cache operation during block fetch transactions.

The CW33000 automatically caches the data (if the system includes a D-cache) or instructions fetched during a block fetch transaction as follows. The CW33000 requests a block fetch transaction by asserting BFREQP...
whenever a cache miss occurs. If the fetch is from the CW33000 DRAM Controller address space and the Controller is configured for block fetch transactions (that is, the BFD bit in the Configuration Register is set to zero), then the Controller acknowledges the request by asserting BFTCHN. The CW33000 then caches the fetched instruction or data, regardless of the state of the CACHDN signal. When the cache miss is in non-DRAM address space, the external memory system asserts BFTCHN to acknowledge the request and the CW33000 then caches the fetched instruction or data, regardless of the state of the CACHDN signal. If either the internal or external memory system does not acknowledge the block fetch request, the CW33000 does not perform the block fetch; instead, it uses the state of CACHDN to determine whether to cache the fetched word. If the memory access us in kseg1 (non-cacheable address space), the CW33000 does not request a block fetch and the fetched word is never cached.

I-Cache Differences

The CW33000 I-cache size is 4 Kbytes. Changing the size of the I-cache impacts the Instruction Address fields as explained below. Note that the I-cache word width does not change.

Figure 2.2 shows the Instruction Address formats for the 8K and 4K I-caches; notice that the Cache Tag ID gets larger and the Line Number smaller as the cache size decreases. The Line Number is smaller because the 4K I-cache has half the number of lines of the 8K I-cache. The Cache Tag ID gets larger because the CW33000 address space has twice as many lines, relative to the 4K I-cache, as it did relative to the 8K I-cache.

Because the Instruction Cache Tag consists of both the Cache Tag ID and the valid bits, its format depends on the I-cache size as well. The Instruction Cache Tag changes as shown in Figure 2.3.
Instruction Cache Tag Format as a Function of I-Cache Size

Note that the I-cache tag and valid bits must be initialized during CW33000 simulation, whether or not they are used in the simulation.

D-Cache Differences

The D-cache, as mentioned previously, is optional in CW33000-based designs. Figure 2.4 shows the details of the D-cache interconnection to the CW33000.

Note that at reset, hardware sets the DCD (Data Cache Disable) bit, bit 22 in the Configuration Register, to zero (D-cache enabled). Therefore, the Reset Handler must set DCD to one to disable all D-cache operations when no D-cache is present in a CW33000-based design. When DCD equals one, the CW33000 loads/stores all data directly from/to the addressed memory (off-chip memory or, if present, on-chip memory). Also, when DCD equals one, the DBS (Data Cache Block Size) bits, 18 and 19 in the Configuration Register, are ignored.

In systems with no D-cache, the state of the CACHDN (Cacheable Data) signal only affects the cacheability of data for the I-cache. In addition, the
DCTSTP (Data Cache Access) signal must be tied LOW in systems with no D-cache.

**Implementation Note**

If the system design includes a D-cache, then the D-cache tag and valid bits must be initialized during CW33000 simulation, whether or not they are used in the simulation.

### 2.6 Counter/Timers

The CW33000 counter/timer operation is identical to that in the LR33000, as described in Chapter 7 of the *LR33000 Self-Embedding Processor User's Manual*.

### 2.7 Signal Definitions

The CW33000 signal names differ from those of the LR33000. Although the signal names are similar, the CW33000 signal names do not use overbars; instead they append an N to all active-LOW signal names and a P to all active-HIGH signal names. In addition, many of the LR33000 bidirectional signals are separated into input and output signals in the CW33000. Refer to Chapter 3 of this manual for complete signal descriptions.

### 2.8 DRAM Controller Operation

The CW33000 DRAM Controller operation is identical to that in the LR33000, as described in Chapter 9 of the *LR33000 Self-Embedding Processor User's Manual*.

### 2.9 I/O Interface Operation

The I/O interface operation differs from that in the LR33000. As mentioned above, most of the LR33000 bidirectional signals are separate input and output signals on the CW33000. In addition, the CW33000 includes the Direct CPU Data Bus Interface (DCDBI), while the LR33000 does not. Refer to Chapter 5 of this manual for a complete I/O interface description.

### 2.10 Specifications

The AC timing for the CW33000 is somewhat similar to that of the LR33000, primarily because many of the signal dependencies are the same in the standard part and the building block. Changes at the periphery of the CW33000 building block, however, including the lack of input, output, and bidirectional buffers and the addition of the DCDBI, have altered the timing. Chapter 6 of this document contains complete AC timing for the CW33000, including the DCDBI timing, as well as specific loading information for all inputs and outputs.
Chapter 3
Signal Definitions

This chapter describes the signals that comprise the CW33000's bit-level interface to other building blocks. The signals are grouped by function; within each functional group, the signals are described in alphabetical order by mnemonic. Each signal definition contains the mnemonic and the full signal name. Note that in the signal descriptions, the verb assert means to drive TRUE or active. The verb deassert means to drive FALSE or inactive.

The signal names used in this document are those used in the design database. The signal naming convention is that signal names for active HIGH signals end in P (positive) and signal names for active LOW signals end in N (negative).

The chapter is divided into these sections:

- Memory Interface Signals
- Direct CPU Data Bus Interface Signals
- Bus Arbitration Signals
- Peripheral Interface Signals
- Status Signals
- Miscellaneous Signals
- Data Cache Signals

Figure 3.1 shows the logic symbol for the CW33000, and Table 3.1 lists the CW33000 signal names and their equivalent signal names on the LR33000. Note that various signals that are bidirectional on the LR33000 (for example, the data bus D[31:0] and the address bus A[31:0]) are separate input and output signals on the CW33000 (DIP[31:0] and DOP[31:0], AIP[31:0] and AOP[31:0]). A CoreWare-based design should include bidirectional buffers on all of these separate inputs and outputs, controlled by the appropriate enable control signals. Figure 3.2 shows some sample bidirectional buffer configurations. Table 3.2 summarizes the buffer enable control signals and the I/O signals they control.
Figure 3.1
CW33000 Logic Symbol

Memory Interface Signals

Direct CPU Data Bus Interface Signals

Note 1: Though these signals are shown as outputs, CDATAP[31:0] are functionally bidirectional signals and CDPARP[3:0] are inputs. Refer to the individual signal descriptions for details.
### Table 3.1
**CW33000/LR33000 Signal Naming**

<table>
<thead>
<tr>
<th>CW33000 Signal Names</th>
<th>LR33000 Equivalent</th>
<th>Signal Summary</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Memory Interface</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>AIP[31:0], AOP[31:0]</td>
<td>A[31:0]</td>
<td>Input and Output Address Buses</td>
</tr>
<tr>
<td>ASIN, ASON</td>
<td>AS</td>
<td>Input and Output Address Strobe</td>
</tr>
<tr>
<td>BERRN</td>
<td>BERR</td>
<td>Bus Error</td>
</tr>
<tr>
<td>BFREQIP, BFREQOP</td>
<td>BFREQ</td>
<td>Input and Output Block-Fetch Request</td>
</tr>
<tr>
<td>BFTCHN</td>
<td>BFETCH</td>
<td>Block Fetch</td>
</tr>
<tr>
<td>BIDENN</td>
<td>—</td>
<td>Enable (Low) or 3-State (High) MXSN, WRN[3:0], AOP[31:0], ASIN, RTON, DTON, BFREQOP</td>
</tr>
<tr>
<td>BWIDEN</td>
<td>BWIDE</td>
<td>Byte-Wide Port</td>
</tr>
<tr>
<td>CACHDN</td>
<td>CACHD</td>
<td>Cacheable Data</td>
</tr>
<tr>
<td>DBENN</td>
<td>—</td>
<td>Enable (Low) or 3-State (High) DOP[31:0], DPOP[3:0]</td>
</tr>
<tr>
<td>DCASN</td>
<td>DCAS</td>
<td>DRAM Column Address Strobe</td>
</tr>
<tr>
<td>DIP[31:0], DOP[31:0]</td>
<td>D[31:0]</td>
<td>Input and Output Data Bus</td>
</tr>
<tr>
<td>DMXSP</td>
<td>DMXS</td>
<td>DRAM Mux Select</td>
</tr>
<tr>
<td>DOEN</td>
<td>DOE</td>
<td>DRAM Output Enable</td>
</tr>
<tr>
<td>DPIP[3:0], DPOP[3:0]</td>
<td>DP[3:0]</td>
<td>Input and Output Data Parity</td>
</tr>
<tr>
<td>DRASN</td>
<td>DRAS</td>
<td>DRAM Row Address Strobe</td>
</tr>
<tr>
<td>DRDYN</td>
<td>DRDY</td>
<td>Data Ready</td>
</tr>
<tr>
<td>EPSELN</td>
<td>EPSEL</td>
<td>EPROM Select</td>
</tr>
<tr>
<td>IOSELN</td>
<td>IOSEL</td>
<td>I/O Select</td>
</tr>
<tr>
<td>MXSN</td>
<td>MXS</td>
<td>Memory Transaction</td>
</tr>
<tr>
<td>PENN</td>
<td>PEN</td>
<td>Parity Enable</td>
</tr>
<tr>
<td>PERRP</td>
<td>PERR</td>
<td>Parity Error</td>
</tr>
<tr>
<td>RDIN, RDON</td>
<td>RD</td>
<td>Input and Output Read Strobe</td>
</tr>
<tr>
<td>RTIN, RTON</td>
<td>RT</td>
<td>Input and Output Read Transaction</td>
</tr>
<tr>
<td><strong>Data Cache Data, Tags, and Valid Bits</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ADDATP[7:0]</td>
<td>—</td>
<td>Data Address for the D-Cache</td>
</tr>
<tr>
<td>ADTAGVALP[5:0]</td>
<td>—</td>
<td>Address for the Cache Tags and Valid Bits</td>
</tr>
<tr>
<td>CSDATP</td>
<td>—</td>
<td>Chip Select for the D-Cache</td>
</tr>
</tbody>
</table>

*(Sheet 1 of 3)*
### Table 3.1 (Continued)
**CW33000/LR33000 Signal Naming**

<table>
<thead>
<tr>
<th>CW33000 Signal Names</th>
<th>LR33000 Equivalent</th>
<th>Signal Summary</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Data Cache Data, Tags, and Valid Bits (continued)</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>DIDATP[31:0]</td>
<td>—</td>
<td>Data Input from the D-Cache</td>
</tr>
<tr>
<td>DITAGP[21:0]</td>
<td>—</td>
<td>Cache Tags Input from the D-Cache</td>
</tr>
<tr>
<td>DIVALP[3:0]</td>
<td>—</td>
<td>Valid Bits Input from the D-Cache</td>
</tr>
<tr>
<td>DOTAGP[21:0]</td>
<td>—</td>
<td>Cache Tags Output to the D-Cache</td>
</tr>
<tr>
<td>DOVALP[3:0]</td>
<td>—</td>
<td>Valid Bits Output to the D-Cache</td>
</tr>
<tr>
<td>OETAGVALDATP</td>
<td>—</td>
<td>Output Enable for the D-Cache Data, Tags, and Valid Bits</td>
</tr>
<tr>
<td>WEDATP[3:0]</td>
<td>—</td>
<td>Data Write Enable (byte-wise) for the D-Cache</td>
</tr>
<tr>
<td>WETAGP</td>
<td>—</td>
<td>Tag Write Enable (byte-wise) for the D-Cache</td>
</tr>
<tr>
<td>WEVALP[3:0]</td>
<td>—</td>
<td>Valid Bit Write Enable (byte-wise) for the D-Cache</td>
</tr>
<tr>
<td><strong>Bus Arbitration</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BGNTP</td>
<td>BGNT</td>
<td>Bus Grant</td>
</tr>
<tr>
<td>BREQN</td>
<td>BREQ</td>
<td>Bus Request</td>
</tr>
<tr>
<td>DCTSTP</td>
<td>D$TST</td>
<td>D-Cache ($) Access</td>
</tr>
<tr>
<td>DMACN</td>
<td>DMAC</td>
<td>DMA Cycle</td>
</tr>
<tr>
<td>DMARN</td>
<td>DMAR</td>
<td>DMA Request</td>
</tr>
<tr>
<td>ICTSTP</td>
<td>I$TST</td>
<td>I-Cache ($) Access</td>
</tr>
<tr>
<td><strong>Peripheral Interface</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>INTP[5:0]</td>
<td>INT[5:0]</td>
<td>Interrupt</td>
</tr>
<tr>
<td>RTACKP</td>
<td>RTACK</td>
<td>Refresh Timer Acknowledge</td>
</tr>
<tr>
<td>RTMOUTN</td>
<td>RTO</td>
<td>Refresh Timeout</td>
</tr>
<tr>
<td>T2ENP</td>
<td>T2EN</td>
<td>Timer Two Enable</td>
</tr>
<tr>
<td>T2TOP</td>
<td>T2TO</td>
<td>Timer Two Timeout</td>
</tr>
<tr>
<td><strong>Direct CPU Data Bus Interface</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BHIGHZN</td>
<td>—</td>
<td>Force CDATAP[31:0] and CDPARP[3:0] to High Impedance</td>
</tr>
<tr>
<td>BRESETP</td>
<td>—</td>
<td>Reset</td>
</tr>
<tr>
<td>CDACCP[1:0]</td>
<td>—</td>
<td>CPU Data Access Type</td>
</tr>
<tr>
<td>CDAP[31:0]</td>
<td>—</td>
<td>CPU Address Bus</td>
</tr>
<tr>
<td>CDATAP[31:0]</td>
<td>—</td>
<td>CPU Data Bus (bidirectional)</td>
</tr>
</tbody>
</table>

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### CW33000 Signal Names

<table>
<thead>
<tr>
<th>CW33000 Signal Names</th>
<th>LR33000 Equivalent</th>
<th>Signal Summary</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Direct CPU Data Bus Interface (continued)</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDPARP[3:0]</td>
<td>—</td>
<td>CPU Data Bus Parity Bits</td>
</tr>
<tr>
<td>CMDREQP</td>
<td>—</td>
<td>CPU Memory Data Request</td>
</tr>
<tr>
<td>CMDRINV</td>
<td>—</td>
<td>CPU Memory Data Request Invalidate</td>
</tr>
<tr>
<td>CSTREQP</td>
<td>—</td>
<td>CPU Store Request</td>
</tr>
<tr>
<td>OCMSELN</td>
<td>—</td>
<td>Direct CPU Data Bus Interface Selected (for OCMem)</td>
</tr>
<tr>
<td>ODBREQP</td>
<td>—</td>
<td>OCMem Data Bus Request</td>
</tr>
<tr>
<td><strong>Status</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BRtAKNP</td>
<td>BRTKN</td>
<td>Branch Taken</td>
</tr>
<tr>
<td>DTIN, DTON</td>
<td>DT</td>
<td>Input and Output Data Transaction</td>
</tr>
<tr>
<td>STALLN</td>
<td>STALL</td>
<td>Stall</td>
</tr>
<tr>
<td>TDONEP</td>
<td>TDONE</td>
<td>Test Mode Transaction Done</td>
</tr>
<tr>
<td><strong>Miscellaneous</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BENDNP</td>
<td>BENDN</td>
<td>Big Endian</td>
</tr>
<tr>
<td>FRCMN</td>
<td>FRCM</td>
<td>Force a Cache Miss</td>
</tr>
<tr>
<td>HIGHZN</td>
<td>HIGHZ</td>
<td>Force All Outputs to High Impedance</td>
</tr>
<tr>
<td>HIGHZIOP</td>
<td>—</td>
<td>Enable (Low) or 3-state (High) BGNTP, BRTAKNP, DCASN, DMACN, DMSXSP, DOEN, DRASN, EPSELN, IOSELN, PERRP, RESETN, RTMOUTN, STALLN, TDONEP, THITP, T2TOP</td>
</tr>
<tr>
<td>RESETN</td>
<td>RESET</td>
<td>Reset</td>
</tr>
<tr>
<td>PCLKP</td>
<td>SYSCCLK</td>
<td>System Clock</td>
</tr>
<tr>
<td>THITP</td>
<td>THIT</td>
<td>Test Hit in the I-Cache or D-Cache</td>
</tr>
</tbody>
</table>

(Sheet 3 of 3)
Table 3.2 Enable Control Signals

<table>
<thead>
<tr>
<th>Enable Control Signal</th>
<th>Affected Signals</th>
</tr>
</thead>
<tbody>
<tr>
<td>BIDENN</td>
<td>AOP[31:0], ASON, BFREQOP, DTON, MXSN, RDON, RTON, WRN[3:0]</td>
</tr>
<tr>
<td>DBENN</td>
<td>DOP[31:0], DPOP[3:0]</td>
</tr>
<tr>
<td>HIGHZIOP</td>
<td>BGNT, BRTAKNP, DCASN, DMACN, DMXSP, DOEN, DRASN, EPSLN, IOSELN, PERRP, RTMOUTN, STALLN, TDONEP, THITP, T2TOP</td>
</tr>
</tbody>
</table>
This section describes the CW33000's memory interface, which consists of a 32-bit Address Bus, a 32-bit Data Bus, and the control signals required to regulate transactions with memory and I/O subsystems. The memory interface also contains the signals required to control DRAM arrays directly. The Direct CPU Data Bus Interface signals, which provide fast communication between the CW33000 CPU and a user-designed on-chip memory, are described in the next section.

**AIP[31:0], AOP[31:0] Address Bus [31:0]**
Input, Output
When it is bus master, the CW33000 uses AOP[31:0] to transmit instruction and data addresses to the memory and peripherals. When another device owns the bus, the CW33000 snoops addresses generated by the bus master on AIP[31:0] (if CACHDN is asserted).

**ASIN, ASON Address Strobe**
Input, Output
The address strobe signals indicate that a valid address is present on the Address Bus. During memory transactions as bus master, the CW33000 asserts ASON one-half cycle after it asserts MXSN.

When the CW33000 is not bus master, it monitors ASIN to determine when a valid address is present on the Address Bus. The CW33000 uses the addresses generated by other bus masters for cache snooping and invalidation, and for DRAM Controller operations.

**BERRN Bus Error**
Input
External logic asserts this signal to indicate that an exceptional condition has occurred. When BERRN is asserted, the CW33000 terminates the current memory transaction and takes a Bus Error Exception. Note that the external logic should assert BERRN until the CW33000 deasserts ASON. Also, when the CW33000 is byte-gathering and a bus error occurs, the external system must assert BERRN during only the first byte transaction (as it would during a single byte fetch); it must not assert BERRN during the second, third, or fourth byte transactions.

**BFREQIP, BFREQOP Block-Fetch Request**
Input, Output
The CW33000 asserts BFREQOP to indicate that it wants to perform a block-fetch transaction when a cache miss occurs, cache is enabled, and the data is in cacheable space. An external bus master asserts BFREQIP when it needs to use the CW33000 memory controller to perform a block-fetch transaction.
BFTCHN  Block Fetch  Input
When the CW33000 asserts BFREQOP, external memory control logic asserts BFTCHN to indicate that the CW33000 can expect a block transfer from memory. BFTCHN must be asserted for the duration of the block-fetch transaction, that is until ASON is deasserted.

When the CW33000’s DRAM Controller is used to manage memory, the DRAM Controller acknowledges the BFREQOP signal internally and automatically. Unless there is an external device that is capable of block-fetch transactions, BFTCHN should be tied to VDD when using the internal DRAM Controller.

BIDENN  Bidirectional Enable  Output
This signal is the bidirectional enable control signal for these CW33000 outputs: AOP[31:0], ASON, BFREQOP, DTON, MXSN, RDON, RTON, WRN[3:0]. When LOW, it enables them; when HIGH, it 3-states them.

BWIDEN  Byte-Wide Port  Input
External logic asserts BWIDEN to indicate that the memory interface is eight bits wide. When BWIDEN is asserted, the CW33000 executes four memory cycles with sequential byte addresses, beginning with the effective address. (The byte-wide feature supports partial-word accesses, but always performs four memory cycles.) If the effective address is not modulo four, the CW33000 wraps around to get all of the bytes in the word in which the effective address falls.

For byte-wide transactions, the CW33000 always takes data from bits D[7:0]. During write transactions, the CW33000 ignores BWIDEN.

CACHDN  Cacheable Data  Input
External logic asserts this signal to indicate that the instruction or data fetched during the current cycle may be stored in the CW33000’s on-chip cache. If CACHDN is not asserted, the CW33000 does not cache the instruction or data fetched during the current transaction unless the transaction is a block fetch. Instructions or data (in systems with a D-cache) fetched during a block fetch are always cached, regardless of the state of CACHDN.

When the CW33000 is not bus master, it monitors this signal to determine whether to perform bus snooping. When CACHDN and ASIN are asserted and RTIN is deasserted, the CW33000 monitors the Address Bus and invalidates the cached word specified by the address. When CACHDN is deasserted, the CW33000 does not perform bus snooping.
DBENN  Data Bus Enable 
Output
The DBENN signal is the bidirectional enable control for the Data Bus and Data Parity Bus. When LOW, it enables them; when HIGH, it 3-states them.

DCASN  DRAM Column Address Strobe  
Output
During a DRAM memory transaction, the CW33000’s DRAM Controller asserts this signal to indicate that the address presented to the DRAM array is the column address.

DIP[31:0], DOP[31:0]  Data Bus [31:0]  
Input, Output
The CW33000 uses the Data Bus to transfer data and instructions to (output) and from (input) memory and peripherals. When another device owns the bus, it may drive or sample these signals.

The CW33000’s byte-ordering mode (endianness configuration) determines the relationship of the Data Bus lines to byte addresses. Figure 3.3 shows the relationship for both big and little endian modes.

![Figure 3.3
Relationship of Data Bus Signal to Byte Addresses](image)

<table>
<thead>
<tr>
<th>Data Bus bits: 31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Byte Address</td>
<td>0</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Big Endian Configuration

<table>
<thead>
<tr>
<th>Data Bus bits: 31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Byte Address</td>
<td>3</td>
<td>2</td>
<td>1</td>
<td>0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The CW33000’s byte-ordering mode (endianness configuration) determines the relationship of the Data Bus lines to byte addresses. Figure 3.3 shows the relationship for both big and little endian modes.

Little Endian Configuration

DMXSP  DRAM Mux Select  
Output
The CW33000’s DRAM Controller outputs DMXSP for the Data Select input of the multiplexers required to multiplex the row and column address from the Address Bus on to the DRAMs’ address bus. When HIGH, DMXSP indicates that the row address should be selected. When LOW, DMXSP indicates that the column address should be selected.
DOEN  DRAM Output Enable  Output
The CW33000's DRAM Controller asserts this signal to enable DRAM data outputs.

DPIP[3:0], DPOP[3:0]  Data Parity [3:0]  Input, Output
The data parity bits allow the CW3300 to check (input) and transmit (output) parity bits for the four data bus bytes as shown in Figure 3.4. The CW33000 uses even parity.

Figure 3.4  Data Bus Parity Bits

<table>
<thead>
<tr>
<th>Data Bus bits:</th>
<th>31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parity Bits</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>(input or output)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The CW33000 always generates parity for write data, and it checks parity for read data when PENN is asserted. When the CW33000 detects a parity error, it asserts the PERRP signal and posts the error in the CPO Status Register.

DRASN  DRAM Row Address Strobe  Output
During a DRAM memory transaction, the CW33000's DRAM Controller asserts this signal to indicate that the address presented to the DRAM array is the row address.

DRDYN  Data Ready  Input
External logic asserts this signal to indicate that it can accept or is providing data. The assertion of DRDYN terminates the memory transaction. Because the CW33000 must wait for external logic to assert DRDYN before it can complete a memory transaction, slow devices can use DRDYN to stall the processor. However, when the automatic wait-state generator is enabled, the CW33000 asserts an internal version of DRDYN to end transactions.

EPSELN  EPROM Select  Output
The CW33000 asserts this signal to indicate that it is accessing the EPSELN address space (0x1F00.0000 to 0x1FFF.FFFF). EPSELN can be used as a chip select. If automatic wait-state generation is
enabled, the CW33000 generates an internal DRDYN signal a programmable number of cycles after the transaction begins. The external PROM logic may override the internal wait-state generator by asserting the DRDYN signal before the programmed number of wait states have passed.

**IOSELN**  
**I/O Select**

The CW33000 asserts this signal to indicate that it is accessing the IOSELN address space (0x1E00.0000 to 0x1EFF.FFFF). IOSELN can be used as a chip select. If automatic wait-state generation is enabled, the CW33000 generates its own DRDYN signal a programmable number of cycles after the transaction begins. The external I/O logic may override the internal wait-state generator and use the DRDYN signal to control the number of wait states.

**MXSN**  
**Memory Transaction Start**

The CW33000 asserts MXSN for one clock cycle at the beginning of a memory transaction to indicate the start of the transaction.

**PENN**  
**Parity Enable**

When asserted by external logic during a read transaction, the CW33000 performs byte-wise checking for even parity on the Data and Data Parity Buses. When deasserted, the CW33000 does not check parity. External logic that is connected to the CW33000’s byte-wide port should never assert PENN.

**PERRP**  
**Parity Error**

The CW33000 asserts PERRP to indicate that it has detected a parity error during the just-completed memory transaction. PERRP can be tied to an interrupt input to cause a parity error exception.

**RDIN, RDON**  
**Read Strobe**

The CW33000, as bus master, asserts RDON to indicate that memory may drive data onto DIP[31:0] during the current read transaction. An external bus master that is using the DRAM Controller asserts RDIN to signal a DMA read and causes the DRAM Controller to assert DOEN.

**RTIN, RTON**  
**Read Transaction**

The CW33000 asserts RTON to indicate that the current memory cycle is a read transaction. The CW33000 deasserts RTON during write transactions. When the CW33000 is not the bus master, the CW33000 monitors RTIN for cache snooping and invalidation.
When the CW33000 is in cache test mode, an external bus master asserts RTIN to request DRAM access, to read or write the CW33000 internal cache.

**WRN[3:0] Byte Write Strobes [3:0] Output**
The CW33000 asserts these signals to indicate that there is valid data on the corresponding segment of the Data Bus. Figure 3.5 shows the relationship of the WRN signals to the Data Bus.
This section provides the signal definitions for the CW33000 Direct CPU Data Bus Interface (DCDBI). Because of the timing-critical nature of this interface to a user-designed on-chip memory, the signals are classified by when and how they are active, as follows.

Signal classification specifies when and how a signal occurs: in particular, during which clock phase the signal is active and whether it is a level-significant or edge-significant signal. Understanding the classification terminology requires a review of the CW33000 instruction execution pipeline.

The pipeline consists of these five stages:

- IF - Instruction Fetch
- RD - Read operands and Decode instructions
- ALU - Perform ALU operations and compute data address
- MEM - Access MEMory
- WB - Write Back the results

Direct CPU Data Bus Interface accesses occur during the ALU and MEM stages. The DCDBI does not, however, need to know the state of the CPU pipeline.

As illustrated in Figure 3.6, each pipeline stage is one clock cycle in duration. Each stage encompasses two phases of the clock, where phase 1 describes the half clock cycle during which the clock is HIGH, and phase 2 refers to the half cycle when the clock is LOW.
Signals are classified as 1s or 2s if they are driven to a known or stable (s) state for the duration of either phase 1 or phase 2 of the clock, respectively. Similarly, signals are classified as 1v or 2v if they become valid (v), with some setup, at the end of either phase 1 or phase 2 of the clock. In the following signal descriptions, signals are classified according to this system.

**BHIGHZN** 3-state Enable Out Output
The CW33000 BIU asserts this signal to force the on-chip memory controller off the CPU Data Bus by 3-stating the on-chip memory output drivers.

**BRESETP** Reset Out Output
The CW33000 asserts this RESET signal for 5 cycles following a LOW-to-HIGH transition of RESETN.

**CDACCP[1:0]** CPU Data Access Type Output
These two bits define the CPU data access type or the size of the data item for the load or store—word, trubyte, halfword, or byte—as follows. (2v)

<table>
<thead>
<tr>
<th>CDACCP[1:0]</th>
<th>Data Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>Byte</td>
</tr>
<tr>
<td>0 1</td>
<td>Halfword</td>
</tr>
<tr>
<td>1 0</td>
<td>Trubyte</td>
</tr>
<tr>
<td>1 1</td>
<td>Word</td>
</tr>
</tbody>
</table>

**CDAP[31:0]** CPU Data Address Bus Output
CDAP[31:0] is the 32-bit, CPU data address bus. (2v)
CDATAP[31:0] CPU Data Bus

The 32-bit, bidirectional CPU data bus transfers data operands to and from the CPU. It must be driven only when the CW33000 is the bus master. Note that this bus is shown in the CW33000 design database as a 3-state output, although functionally it is a 3-state bidirectional bus. See Section 4.2, “Functional Description,” for more details. (2v)

CDPARP[3:0] CPU Data Parity

These four bits are the data parity bits for the shared (bidirectional) bus. The CPU does not monitor data parity. However, when the on-chip memory is the bus master it must drive these signals to some known value, zero in this case, because they cannot be left floating; otherwise, they should be 3-stated. Note that these signals are shown in the CW33000 design database as 3-state outputs, although functionally they are 3-state bidirectional. Refer to Section 4.2, “Functional Description,” for more details. (2v)

CMDREQP CPU Memory Data Request

The memory data request signal validates the memory data address on the CDA bus. (2s)

CMDRINVP CPU Memory Data Request Invalidate

When the CPU asserts the CPU memory data request invalidate signal when an instruction exception occurs. If the exception occurs during the MEM cycle of an access of the on-chip memory, data writes must be disabled to maintain precise handling of instruction cancellation due to exceptions. (1s)

CSTREQP CPU Store Request Direction

The store request direction signal indicates whether the CPU intends to write information to on-chip memory (a CPU store) or read information from on-chip memory (a CPU load). (2s)

OCMSELN On-Chip Memory Selected

The on-chip memory system selected signal tells the BIU that the address on the CDA bus has selected the on-chip memory and that the BIU should ignore the transaction. (2v)

ODBREQP On-Chip Memory Data Bus Request

The on-chip memory system data bus request signal tells the CW33000 bus interface unit (BIU) that the Direct CPU Data Bus Interface will drive data onto the data bus in phase 2 of the next clock cycle. (2v)
This section describes the CW33000 bus arbitration signals. The CW33000 memory interface functions as a general-purpose bus, and these signals allow intelligent peripherals to request bus mastership to perform DMA operations or access the CW33000's on-chip cache memories.

**BGNT** Bus Grant

When the CW33000 grants the bus to a requesting device, it asserts BGNT, BIDENN, and DBENN. When BGNT is asserted, the requesting bus master can control the signals that are 3-stated or enabled by BIDENN and DBENN.

The CW33000 asserts BGNT only when there is no on-going bus transaction. If BREQN is asserted during a transaction, the CW33000 asserts BGNT after the transaction has completed. The requesting logic, therefore, should continue to assert BREQN until the CW33000 grants the bus by asserting BGNT. If both external logic and the CW33000 request the bus simultaneously, external logic has priority.

When the CW33000 has released the bus to another master, it snoops, or monitors bus transactions, to determine if cache entries need to be invalidated. Note that after granting the bus, the CW33000 continues to run. If the CW33000 then needs to use the bus and it is granted to another device, the CW33000 stalls until the bus is available.

**BREQN** Bus Request

External bus masters assert this signal to request control of the Address and Data Buses and the relevant control signals.

**DCTSTP** Data Cache Access

When this signal is asserted, external logic can read and write the CW33000's data cache, if present. In data cache access mode, the external device controls the AIP[31:0], DIP[31:0], ASIN, and RTIN signals.

**DMACN** DMA Cycle

The CW33000 asserts this signal to acknowledge the DMARN and to indicate that the DRAM Controller has started the access for the requesting device. During such DMA accesses, the DRAM Controller manages the DRASN, DCASN, and DMXSP signals. The DMA device must drive the DRAM write strobes, address bus, and data bus; note that this configuration requires multiport RAMs.
During DMA operations by other devices, the CW33000 continues to control and use the Address and Data Buses and data parity bits. If both external logic and the CW33000 need to use the DRAM Controller, they take turns, switching control at the end of each memory transaction.

### DMARN
**DMA Request**
Input
External logic asserts this signal to request use of the CW33000’s DRAM Controller for a DMA access. The DMARN and DMACN signals are not related to the BREQN and BGNTP signals.

### ICTSTP
**Instruction Cache Access**
Input
When this signal is asserted, external logic can read and write the CW33000’s instruction cache. In instruction cache access mode, the external device controls the AIP[31:0], DIP[31:0], ASIN, and RTIN signals.

### 3.4 Peripheral Interface Signals
The CW33000 contains three counter/timers. Two of the three timers can be controlled via the peripheral interface signals described in this section.

### CPCP[3:0]
**Coprocessor Condition [3:0]**
Input
The four Coprocessor Condition signals, CPCP[3:0], carry condition inputs that the CW33000 can separately test using coprocessor branch instructions. Note that the corresponding coprocessor usable bit (Cu[3:0]) in the Status Register must be set in order to test a condition input. Refer to the LR33000 Self-Embedding Processor User’s Manual, Chapter 4, “Exception Processing,” for a description of the Status Register and the Cu bits.

Although the CPCP inputs are tested using coprocessor branch instructions, the CW33000 hardware makes no assumptions about the actual source of these signals. The use of these condition inputs is, therefore, application-dependent.

### INTP[5:0]
**Interrupt [5:0]**
Input
External logic asserts these signals to cause the CW33000 to take an interrupt exception. The state of these signals is reflected in the Cause Register’s IP[5:0] field, which the interrupt exception routine uses to identify the source of the interrupt. Consequently, the interrupting logic should continue to assert the INTP signal until the exception routine has serviced the interrupt.

New interrupts are not recognized by the processor during an interrupt exception. However, the IP[5:0] field in Cause Register continues to reflect the state of INTP[5:0], so software can determine...
whether external logic has requested any additional interrupts since the start of the interrupt exception.

The interrupt inputs can be individually disabled or masked by setting the appropriate bit in the CW33000's Status Register, as described in the LR33000 Self-Embedding Processor User's Manual, Chapter 4, "Exception Processing."

**RTACKP** Refresh Timer Acknowledge Input

External logic asserts RTACKP to indicate that it has completed the refresh operation initiated by the CW33000's assertion of RTMOUTN. The assertion of RTACKP causes the CW33000 to deassert RTMOUTN. External logic must assert RTACKP for two cycles to guarantee the Refresh Timer reset.

**RTMOUTN** Refresh Timeout Output

The CW33000 asserts this signal to indicate that the Refresh Timer has counted down from its preset initial value (RCOUNT) to zero. The CW33000 continues to assert RTMOUTN until external logic asserts RTACKP, but the Timer does not stop running; instead, it loads the RCOUNT value and continues to count.

When the DRAM Controller is enabled, the CW33000 asserts RTMOUTN to indicate that a refresh cycle is in progress. When the DRAM Controller is disabled, external DRAM control logic can use the assertion of RTMOUTN to start a refresh cycle.

Because the user cannot disable the Refresh Timer, there is no way to guarantee that RTMOUTN will stay deasserted. To guarantee, however, that RTMOUTN will be either asserted (LOW) or toggling, set RCOUNT to zero and drive the RTACKP signal LOW or HIGH. The following table summarizes the RTMOUTN states vis-a-vis RTACKP.

<table>
<thead>
<tr>
<th>RCOUNT</th>
<th>RTACKP</th>
<th>RTMOUTN</th>
</tr>
</thead>
<tbody>
<tr>
<td>ZERO</td>
<td>LOW</td>
<td>LOW</td>
</tr>
<tr>
<td>ZERO</td>
<td>HIGH</td>
<td>Toggle</td>
</tr>
</tbody>
</table>

**T2ENP** Timer 2 Enable Input

External logic asserts this signal to enable the operation of Timer 2. Timer 2 counts as long as T2ENP is asserted.
### 3.5 Status Signals

The CW33000 generates four signals that indicate its internal state. Those signals are described in this subsection.

<table>
<thead>
<tr>
<th>Signal</th>
<th>Description</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>T2TOP</strong></td>
<td>Timer 2 Timeout</td>
<td>Output</td>
</tr>
<tr>
<td></td>
<td>The CW33000 toggles T2TOP to indicate that the CW33000’s Timer 2 has counted down from its preset value to zero. T2TOP is set LOW on cold and warm starts.</td>
<td></td>
</tr>
<tr>
<td><strong>BRTAKNP</strong></td>
<td>Branch Taken</td>
<td>Output</td>
</tr>
<tr>
<td></td>
<td>When asserted, this signal indicates that the condition has been met for a branch instruction in the CW33000 pipeline. The CW33000 signals a branch during the ALU stage of the pipeline, which is when the control transfer occurs.</td>
<td></td>
</tr>
<tr>
<td><strong>DTIN, DTON</strong></td>
<td>Data Transaction</td>
<td>Input, Output</td>
</tr>
<tr>
<td></td>
<td>When bus master, the CW33000 asserts DTON to indicate that the current bus transaction is a data read or write. The CW33000 deasserts this signal to indicate that the current bus transaction is an instruction fetch.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>When an external device is bus master (BGNTP asserted), the external device uses DTIN to select the block size field for block transactions. When DTIN is asserted, the DRAM Controller uses the Data Cache Block Size (DBS) to determine the number of words to transfer. When DTIN is deasserted, the DRAM Controller uses the Instruction Cache Block Size (IBS) field. For a complete description of the block size fields, refer to the Configuration Register subsection in Chapter 6 of the LR33000 Self-Embedding Processor User’s Manual.</td>
<td></td>
</tr>
<tr>
<td><strong>STALLN</strong></td>
<td>CPU Pipeline Stall</td>
<td>Output</td>
</tr>
<tr>
<td></td>
<td>The CW33000 asserts this signal to indicate that it is in a stall state. Note that when the CPU asserts STALLN, the on-chip memory must follow the CPU stall protocol as described in Chapter 4 of this manual. Note also that STALLN is a performance-critical signal, so the designer must minimize the external load on STALLN to assure maximum performance. (1s)</td>
<td></td>
</tr>
<tr>
<td><strong>TDONEP</strong></td>
<td>Test Mode Transaction Done</td>
<td>Output</td>
</tr>
<tr>
<td></td>
<td>The CW33000 asserts this signal to indicate that a cache access mode read or write operation is complete.</td>
<td></td>
</tr>
</tbody>
</table>
The CW33000 has six miscellaneous inputs, described next.

**BENDNP**  **Big Endian Byte Ordering**  **Input**
When RESETN is asserted, the BENDNP signal specifies the byte ordering for the CW33000: big-endian if BENDNP is tied HIGH, or little-endian if BENDNP is tied LOW. If the CW33000-based chip includes an on-chip memory, then this signal must also input to the on-chip memory. Refer to Section 4.4, "Data Formats and Addressing," for a complete description of the use of BENDNP to specify data formats. Note that BENDNP is a static signal; do not change its state when RESETN is deasserted.

**FRCMN**  **Force Cache Miss**  **Input**
When external logic asserts FRCMN, the CW33000 detects a cache miss on the current instruction fetch. This signal is intended for test and in-circuit emulation purposes.

**HIGHZN**  **High Impedance**  **Output**
This HIGH-Z signal controls the 3-state enable signals DBENN, BIDENN, and HIGHZIOP. In addition, HIGHZN selects between warm and cold processor starts after reset. When HIGHZN and RESETN are asserted together, the CW33000 executes a cold start after RESETN is deasserted. When RESETN is asserted alone, the CW33000 executes a warm start. The DRAM Controller is not initialized on a warm start and the DRAM contents remain valid.

**HIGHZIOP**  **High Impedance I/O Enable**  **Output**
This signal is the bidirectional enable control signal for these CW33000 outputs: BGNTP, BRTAKNP, DCASN, DMACN, DMXSP, DOEN, DRASN, EPSELN, IOSELN, PERRP, RESETN, RTMOUTN, STALLN, TDONEP, THITP, T2TOP. When HIGH, HIGHZIOP 3-states these signals; when LOW, it enables them.

**RESETN**  **Reset**  **Input**
A LOW-to-HIGH transition of RESETN initializes the processor and initiates a non-maskable RESETN exception. Driving RESETN LOW does not halt the processor or cause any other action. Only a LOW-to-HIGH transition of RESETN initializes the processor.

The RESET Exception should vector the processor to a pre-defined bootstrap routine (typically, PROM-resident) that initializes the system. The RESET jump address is different from that used by interrupts, and RESETN (unlike interrupts) forces the CW33000 out of any wait loops. Refer to the LR33000 Self-Embedding Processor.
User's Manual, Chapter 4, "Exception Processing," for a detailed description of the CW33000’s response to the RESET Exception. Note that RESETN need not be synchronized with PCLKP, but PCLKP must be active for RESETN to take effect.

### PCLKP

**Clock Signal**

PCLKP is the CW33000 system clock.

### THITP

**Test Hit**

The CW33000 asserts THITP during a read of its instruction or data caches in cache access mode to indicate that the cache tags matched the address of the read. This signal is intended for test purposes.

---

### 3.7 Data Cache Signals

This section describes the signals that interface the CW33000 with the optional data cache (D-cache). The D-cache consists of three parts: the data, the tags, and the valid bits. The signals for each part utilize these naming conventions:

- AD in a signal name refers to the D-cache Address
- DI refers to data in to the CW33000 from the D-cache
- DO refers to data out from the CW33000 to the D-cache
- OE is an output enable
- WE is a write enable
- DAT is appended to data signals
- TAG is appended to tag signals
- VAL is appended to valid bit signals

The signals are described briefly below. Recall that the data input to the D-cache is through the Direct CPU Data Bus Interface, while the D-cache data output is to the D-cache controller.

#### ADDAT[7:0]

**Data Address**

These eight bits are the data address from the CW33000 for the D-cache.

#### ADTAGVAL[5:0]

**Cache Tag and Valid Bit Address**

These six bits are the address outputs from the CW33000 to the D-cache for the Cache Tags and Valid Bits.

#### CSDAT

**D-Cache Select**

This chip select signal selects the D-cache for access.
DOTAG[21:0]  Cache Tag Out        Output
               These 22 bits provide the Cache Tags to the D-cache.

DOVAL[3:0]    Valid Bit Out       Output
               These four signals provide the Valid Bits for the D-cache.

DIDAT[31:0]   Data Bus In         Input
               These signals are the data bus inputs from the D-cache.

DITAG[21:0]   Cache Tag In        Input
               These D-cache Cache Tags signals are input from the D-cache.

DIVAL[3:0]    Valid Bit In        Input
               These four Valid Bits are input from the D-cache.

WEDAT[3:0]    Data Write Enable   Output
               These four bits provide the byte-wise write enable for the data part of
               the D-cache.

OETAGVALIDAT Tag and Valid Bit Write Enable Output
               This signal is the output enable for the Cache Tags and Valid Bits in
               the D-cache.

WETAG        Cache Tag Write Enable Output
               This signal is the write enable for the Cache Tags part of the D-cache.

WEVAL[3:0]    Valid Bit Write Enable Output
               These four signals provide the write enable for the Valid Bits part of
               the D-cache.
Chapter 4
Direct CPU Data Bus Interface

The CW33000 provides two interfaces to instruction and/or data operands. The Bus Interface Unit (BIU) offers access to a wide variety of instruction and data sources of various speeds, including fast or slow ROM or DRAM, as well as the flexibility to program the timing parameters required to access each source. The Direct CPU Data Bus Interface (DCDBI) is a fast, dedicated interface for data operands only. It is much less flexible than the BIU, but it is far faster. This chapter describes the Direct CPU Data Bus Interface and explains its use.

Sections in this chapter are:

- Overview
- Functional Description
- DCDBI Timing
- Data Formats and Addressing

4.1 Overview

The CW33000 BIU offers access for both data and instruction operands from SRAM, DRAM, PROM, and I/O, as well as flexibility in programming the timing components for each type of data access. However, accessing data through the BIU requires more than one CPU cycle and therefore generates CPU pipeline stalls.

The Direct CPU Data Bus Interface provides direct communication between the CPU inside the CW33000 and a customer-designed on-chip memory that is physically on-chip but not part of the CW33000, without involving the BIU. This dedicated interface enables the CPU to access on-chip memory data in a single cycle with no CPU pipeline stalls, at the expense of data source selection and timing flexibility.

Figure 4.1 shows a block diagram of the Direct CPU Data Bus Interface in the CW33000.
The important characteristics of the Direct CPU Data Bus Interface are:

- The Direct CPU Data Bus Interface can supply only data operands to the CPU, even though the CW33000 CPU has separate address and data buses for both data operands and instruction operands.

- The user must assign an address space to the on-chip memory. This on-chip memory address space and the address space that is accessible through the BIU must be separate.

- The access time for the user-designed on-chip memory must be less than the clock cycle time of the CW33000.

- The on-chip memory system must decode its addresses from the CPU Data Address Bus, CDAP[31:0], and assert the on-chip memory selected signal, OCMSELN, to signal the CW33000 when an address match occurs.

- The CPU asserts STALLN to notify the on-chip memory of a CPU pipeline stall. If the CPU stalls during an access to the on-chip memory, then the on-chip memory must stay synchronized with the stalled CPU pipeline.

- The on-chip memory system must recognize and handle exceptions in a precise manner.
4.2 Functional Description

This section provides a functional overview of the Direct CPU Data Bus Interface (DCDBI). It discusses these topics:

- Memory Accesses
- Reset Handling
- CPU Stall Handling
- Exception Handling

The remaining sections in this chapter provide a more detailed description of the DCDBI.

Memory Accesses

Recall the CPU pipeline stages:

<table>
<thead>
<tr>
<th>IF</th>
<th>RD</th>
<th>ALU</th>
<th>MEM</th>
<th>WB</th>
</tr>
</thead>
</table>

Recall also that the on-chip memory must be assigned an address space, as discussed in Section 2.4, "Memory System Architecture." This address space and the remaining address space that is accessible through the BIU must be separate.

During the ALU stage of the pipeline, the CPU computes and presents the address of data operands for access on CDAP[31:0]. The on-chip memory decodes the memory address, and the CPU and the on-chip memory present the appropriate control signals:

- CDACCP[1:0], from the CPU, specifies the data type: byte, halfword, tribyte, or word.
- CSTREQP, from the CPU, defines whether the access is a load or store.
- CMDREQP, from the CPU, validates the memory data address.
- Either CDBREQP (an internal signal from the CPU to the BIU) or ODBREQP (from the on-chip memory) notifies the BIU that a bus master will drive the data bus on the following cycle.
OCMSELN, from the on-chip memory, notifies the BIU that the on-chip memory has been addressed. Because the BIU is unaware of the on-chip memory's address space, it attempts to handle any memory request for data. When the on-chip memory asserts OCMSELN, the BIU does not respond to the CPU's memory data request.

During the MEM stage, either the CPU drives data onto the data bus (CDATAP[31:0]) for a store to the on-chip memory or the on-chip memory drives the data for a CPU load. The current bus master must also drive the data parity bus, CDPARP[3:0], during this stage. The CPU does not check data parity; however, because data parity is a 3-state bus, it must be driven to some known value. In particular, when the on-chip memory is the data bus master during a CPU load from on-chip memory, it must drive CDPARP[3:0] at the same time it drives CDATAP[31:0]. At the end of phase 2 of the MEM stage, either the CPU or on-chip memory latches the data on the data bus.

If a stall occurs during the ALU stage, the CPU asserts the stall signal STALLN as a 1s signal of the following MEM stage; STALLN prevents the CPU and on-chip memory from latching the data. One or more stall cycles then occur, and the CPU and the on-chip memory must re-drive all of the above control signals for the duration of the stall.

If an exception occurs during the ALU stage, the CPU asserts a memory data request invalidate signal (CMDRINVP) as a 1s signal in the MEM stage to inhibit the latching of CPU data into the on-chip memory.

If a stall occurs during the MEM stage, the stall signal is asserted as a 1s signal of the following WB stage, and both the data bus and the data parity bus must be re-driven for the duration of the stall.

Refer to Section 4.3 for details on CPU store/load operations to/from the on-chip memory.

Note that all data transfers between the CPU and the on-chip memory must be 32-bits wide. The data access bits, CDACCP[1:0], and the two low-order address bits, CDAP[1:0], define which bytes are valid in the 32-bit word, as discussed in Section 4.4.

CDATAP[31:0] and CDPARP[3:0] are pictured in Chapter 2 and shown in the CW33000 design database as 3-state outputs, although functionally CDATAP[31:0] is a 3-state bidirectional bus and CDPARP[3:0] are 3-state inputs. This approach is required because in designs with no on-chip mem-
ory and no D-cache these signals are left unconnected, and leaving 3-state inputs or bidirects unconnected generates errors in the LCMP program and causes the LLINK program to abort. Follow these guidelines to avoid problems. For systems with on-chip memory and D-cache, (that is, systems that use the signals), connect the signals to 3-state drivers. The LSED program will report WARNING – net drives no inputs (which is not a problem), the LCMP program will report WARNING – multiple output connections (which is also not a problem), and the LLINK program has no problem with this solution. For systems that do not use on-chip memory or D-cache, leave the signals unconnected. Because the signals are 3-state outputs, this approach generates no conflicts or errors in the LCMP, LSED, and LLINK programs.

**Implementation Note**

Note that STALLN is a performance-critical signal, so any external loading on STALLN affects the CW33000 internal nodes. Take care, therefore, to keep the external loading on STALLN at an absolute minimum to assure maximum performance; that is, buffer STALLN if used and place the buffer as close as possible to the CW33000 core at layout.

**Reset Handling**

When the CW33000 is reset, it asserts the BRESETP signal to allow the user to initialize the on-chip memory controller.

**CPU Stall Handling**

Although a load/store from/to on-chip memory does not cause a CPU stall, CPU stalls that affect the on-chip memory can occur. When a CPU stall occurs during an on-chip memory access, the on-chip memory system must recognize the stall and keep the load or store operation in step with the stalled CPU pipeline for the duration (one or more cycles) of the stall. The fundamental guideline of stall handling is that during a stall, the CPU and on-chip memory must re-do whatever they were doing prior to the stall; that is, they must re-drive all data and control signals. Note that the on-chip memory system is affected only by CPU stalls that occur during the ALU and MEM cycles, because the CPU issues the on-chip memory access control signals in phase 2 of the ALU cycle and concludes the access in phase 2 of the MEM cycle.

The following descriptions summarize how the on-chip memory system must handle stalls during both CPU loads and stores. Section 4.3, “DCDBI Timing,” provides a more detailed description of stall handling.
**Stall During a RD Cycle** – The sequence of events for a stall that occurs during a RD cycle is as follows.

- During a normal (non-stalled) on-chip memory access, the ALU cycle for the access directly follows the RD cycle. During a RD-cycle stall, however, the CPU address and control signals that would normally occur in that ALU cycle are postponed and, instead, whoever was driving the bus during the RD cycle drives it again with the previous data.
- The on-chip memory access occurs during the first RUN cycle (ALU) after the stall.

**Stall During an ALU Cycle** – A stall during an ALU cycle can affect either a CPU store to the on-chip memory or a CPU load from the on-chip memory. When a stall occurs during the ALU cycle of a store, the following events must occur:

- STALLN disables the storing of new data into the on-chip memory.
- The CPU re-drives the address and control signals for this on-chip memory instruction during the stall.
- The on-chip memory latches the data during the first RUN cycle (that is, the MEM cycle) after the stall.

When a stall occurs during a CPU load from on-chip memory:

- The on-chip memory does not drive data onto the data bus, because the on-chip memory bus drivers are high impedance during the stall.
- The bus master who drove the data bus during the last RUN cycle re-drives the bus with the previous data throughout the stall.
- The CPU and on-chip memory re-issue the address and control signals for the on-chip memory instruction during the stall.
- The on-chip memory must drive the data onto the data bus during the first RUN cycle (the MEM cycle) after the stall.

**Stall During a MEM Cycle** – Stalls that occur during a MEM cycle can affect both a CPU store to on-chip memory and a CPU load from on-chip memory. For a MEM-cycle stall during a CPU store to on-chip memory:

- The store to the on-chip memory completes successfully during the initial MEM cycle, which is when the stall occurs, or at any time during the subsequent stall cycles.
The CPU redrives the on-chip memory data from the ALU cycle during the stall, but it does not re-drive the on-chip memory address.

However, for a MEM-cycle stall during a CPU load from on-chip memory:

- The on-chip memory must drive valid on-chip memory data to the CPU during the MEM cycle in which the stall occurs. In addition, the on-chip memory must acknowledge the CPU stall and re-drive the data bus, parity bus, and appropriate control signals for the duration of the stall.

The on-chip memory system must handle instruction cancellation due to an exception in a precise manner. Note that only an exception that occurs during the ALU cycle of a CPU store can cancel an on-chip memory access.

As summarized in Figure 4.2, if a CPU exception occurs prior to the ALU stage of an on-chip memory transaction instruction, the CPU inhibits the memory data request (CMDREQP) for the exceptional instruction, effectively cancelling the on-chip memory access because the on-chip memory never sees a valid request.

If a CPU exception occurs during the ALU stage of an on-chip memory transaction instruction, the CPU asserts the memory data request invalidate signal (CMDRINVP). If the exceptional instruction is for a CPU store to the on-chip memory, then the on-chip memory must disable the store at this point; it is not required, however, to disable a CPU load. If a stall follows the exception, the CPU asserts the CMDRINVP signal for the duration of the stall.

If an exception occurs during the MEM stage of a load from on-chip memory, the CPU inhibits the loading of the on-chip memory data to its general registers during the WB stage. Note that the on-chip memory must drive the data bus in this case to keep it from floating. An exception that occurs...
During the MEM stage of a store to on-chip memory does not affect the store.

### 4.3 DCDBI Timing

This section discusses in detail the CW33000 DCDBI. It includes detailed timing diagrams and descriptions for CPU load and store functions to and from the on-chip memory; it also includes both stall and exception timing information.

The section illustrates these transactions:

- CPU Store Timing (Figure 4.3)
- CPU Load Timing (Figure 4.4)
- CPU Store, Stall During ALU Stage (Figure 4.5)
- CPU Load, Stall During ALU Stage (Figure 4.6)
- CPU Store, Stall During MEM Stage (Figure 4.7)
- CPU Load, Stall During MEM Stage (Figure 4.8)
- CPU Store with an Exception During the ALU Stage (Figure 4.9)
- CPU Store with an Exception (ALU Stage) and a Stall (MEM Stage) (Figure 4.10)

A detailed explanation of each transaction is followed by a figure that illustrates the transaction. Note that references in the figures to OCMem are to the customer-designed on-chip memory.

#### CPU Store

- The CPU places the address for the on-chip memory on CDAP[31:0], and sets the value of CDACCP[1:0] to specify to the on-chip memory the data size for the access.

- The CPU asserts both CMDREQP to validate the data address on CDAP[31:0] and CSTREQP to specify the memory request direction, in this case a store (HIGH). For a load request, the CPU drives CSTREQP LOW. Note that the CPU drives both CMDREQP and CSTREQP in the ALU stage to specify an on-chip memory transaction in the subsequent MEM stage.

- The on-chip memory must assert OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The CPU asserts CDBREQP, an internal signal, to notify the BIU that the CPU intends to drive both the data bus, CDATAP[31:0], and the data parity bus, CDPARP[3:0], during the following MEM stage.
- The CPU drives data onto both the data bus and the data parity bus as phase-2-valid (2v) signals during the MEM stage.
- The on-chip memory latches the CPU data at the end of the MEM stage. Note that the state of the CW33000 BENDNP signal specifies the endianness of the data, which is determined during initialization and remains unchanged during operation.

**Figure 4.3**
**CPU Store Timing**

<table>
<thead>
<tr>
<th>Signal</th>
<th>ALU Stage</th>
<th>MEM Stage</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCLKP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDAP[31:0]</td>
<td>Data Address X</td>
<td>Address Y</td>
</tr>
<tr>
<td>CDACCP[1:0]</td>
<td>Access Type X</td>
<td>Access Type Y</td>
</tr>
<tr>
<td>CMDREQP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CSTREQP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>OCMSELN</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDBREQP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDATAP[31:0], CDPARP[3:0]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BENDNP</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note:
1. Internal signal shown for reference only.
**CPU Load**

- The CPU places the address for the on-chip memory on CDAP[31:0]. Note that CDACCP[1:0] (not shown) does not affect the on-chip memory during a CPU load because the on-chip memory must always supply a single 32-bit word during a CPU load.

- The CPU asserts CMDREQP to validate the memory data address on the CDA bus.

- The CPU drives CSTREQP LOW to specify the memory request direction, in this case, a load. Recall from the previous example that the CPU asserts CSTREQP (HIGH) to request a store.

- The on-chip memory must assert OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.

- The on-chip memory must assert ODBREQP to notify the BIU that the on-chip memory intends to drive both CDATAP[31:0] and CDPARP[3:0] during the following MEM stage.

- The on-chip memory must drive data on both the data bus and the data parity bus as 2v signals during the MEM stage. Note that while the CPU does not check parity, the on-chip memory must drive CDPARP[3:0] to some value to keep them from floating to an unknown state.
Figure 4.4
CPU Load Timing

<table>
<thead>
<tr>
<th>Signal</th>
<th>ALU Stage</th>
<th>MEM Stage</th>
</tr>
</thead>
<tbody>
<tr>
<td>Phase 1</td>
<td>Phase 2</td>
<td>Phase 1</td>
</tr>
<tr>
<td>PCLKP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDAP[31:0]</td>
<td>Valid Data Address X</td>
<td>Address Y</td>
</tr>
<tr>
<td>CMDREQP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CSTREQP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>OCMSELN</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ODBREQP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDATAP[31:0]</td>
<td>Valid QCMem Data X</td>
<td></td>
</tr>
<tr>
<td>CDPARP[3:0]</td>
<td>Z</td>
<td>Valid</td>
</tr>
</tbody>
</table>

Direct CPU Data Bus Interface 4-11
CPU Store With a Stall During the ALU Stage

- The CPU places the address for the on-chip memory on CDAP[31:0] and sets CDACCP[1:0] to specify for the on-chip memory the data size for the access.
- The CPU asserts both CMDREQP to validate the data address on CDAP[31:0] and CSTREQP to specify the memory request direction, in this case, a store (HIGH).
- The on-chip memory must assert OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The CPU asserts CDBREQP to notify the BIU that the CPU intends to drive both CDATAP[31:0] and CDPARP[3:0] during the following MEM stage.
- A CPU stall occurs, so the next cycle is a STALL cycle instead of the MEM cycle. In this case:
  - The on-chip memory must not latch the data during the STALL cycle(s), because the available data are from a previous instruction.
  - The CPU does not drive the on-chip memory data onto the data bus during the STALL cycle(s); the previous bus owner continues to drive the bus.
  - All signals driven during the initial ALU cycle are re-driven for all STALL cycles.
  - STALL cycles continue until the CPU deasserts STALLN.
- The CPU deasserts STALLN. Then it drives the on-chip memory data onto the data bus and drives the data parity bus as 2v signals during the MEM stage.
- The on-chip memory latches the CPU data at the end of the MEM stage. Recall that the state of the CW33000 BENDNP signal specifies the endianness of the data, which is determined during initialization and remain unchanged during operation.
Figure 4.5
CPU Store, Stall
During ALU Stage

<table>
<thead>
<tr>
<th>Signal</th>
<th>ALU Stage Run Phase 1</th>
<th>ALU Stage Run Phase 2</th>
<th>ALU Stage Stall Phase 1</th>
<th>ALU Stage Stall Phase 2</th>
<th>MEM Stage Run Phase 1</th>
<th>MEM Stage Run Phase 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCLKP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDAP[31:0]</td>
<td>Data Address X</td>
<td>Data Address X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDACCP[1:0]</td>
<td>Access Type X</td>
<td>Access Type X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CMDREQP</td>
<td></td>
<td></td>
<td>X</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CSTREQP</td>
<td></td>
<td></td>
<td>X</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>OCMSELP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDBREQP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDATAP[31:0],</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDPARP[3:0]</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>STALLN</td>
<td></td>
<td></td>
<td></td>
<td>Data Available Here</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BENDNP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note:
1. Internal signal shown for reference only.
CPU Load With a Stall During the ALU Stage

- The CPU places the on-chip memory address on CDAP[31:0].
- The CPU asserts CMDREQP to validate the memory data address on the CDA bus.
- The CPU specifies the memory request direction by driving CSTREQP LOW, requesting a load.
- The on-chip memory asserts OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The on-chip memory asserts ODBREQP to notify the BIU that the on-chip memory intends to drive both CDATAP[31:0] and CDPARP[3:0] during the following MEM stage.
- A CPU stall occurs, so the next cycle is a STALL cycle instead of the normal MEM cycle. In this case:
  - The CPU does not load the on-chip memory data during the STALL cycle(s).
  - The on-chip memory must not drive the data bus during the STALL cycle(s).
  - The CPU and on-chip memory must re-drive all signals driven during the initial ALU cycle for all STALL cycles.
  - STALL cycles continue until the CPU deasserts STALLN.
- The CPU deasserts STALLN.
- The on-chip memory drives data on both the data bus and the data parity bus as 2v signals during the first RUN cycle (that is, the MEM stage) after the STALL.
Figure 4.6
CPU Load, Stall During
ALU Stage

Note:
1. The signal shown with solid lines defines the minimum required functionality. The section indicated by the
dotted lines shows optional functionality.
CPU Store With a Stall During the MEM Stage

- The CPU places the address for the on-chip memory on CDAP[31:0] and sets CDACCP[1:0] to specify the data size for the access.
- CMDREQP validates the memory data address on the CDA bus.
- The CPU specifies the memory request direction by driving CSTREQP HIGH, requesting a store.
- The on-chip memory asserts OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The CPU asserts CDBREQP to notify the BIU that the CPU intends to drive both CDATAP[31:0] and CDPARP[3:0] during the following MEM stage.
- The CPU drives data on both the data bus and the data parity bus as 2v signals during the MEM stage.
- A CPU stall occurs, so the next cycle is a STALL cycle instead of the normal WB cycle. In this case:
  - The on-chip memory may latch the data at end of phase 2 of the stalled MEM cycle or during any of the subsequent stall cycles.
  - All signals driven during the initial MEM cycle are re-driven for all STALL cycles.
  - STALL cycles continue until the CPU deasserts STALLN.
- The CPU deasserts STALLN and the CPU instruction pipeline proceeds to the WB stage.
Figure 4.7
CPU Store, Stall During MEM Stage

<table>
<thead>
<tr>
<th></th>
<th>RUN (ALU Stage)</th>
<th>RUN (MEM Stage)</th>
<th>STALL Cycle(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Phase 1</td>
<td>Phase 2</td>
<td>Phase 1</td>
</tr>
<tr>
<td>PCLKP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDAP[31:0]</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDACC[1:0]</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CMDREQP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CSTREQP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>OCMSELN</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDBREQP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>DATAP[31:0]</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>STALLN</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BENDNP</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note:
1. Internal signal shown for reference only.
CPU Load With a Stall During the MEM Stage

- The CPU places the address for the on-chip memory on CDAP[31:0].
- The CPU asserts CMDREQP to validate the memory data address on the CDA bus.
- The CPU specifies the memory request direction by driving CSTREQP LOW, requesting a load.
- The on-chip memory asserts OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The on-chip memory asserts ODBREQP to notify the BIU that the on-chip memory intends to drive both CDATAP[31:0] and CDPARP[3:0] during the following MEM stage.
- The on-chip memory drives data on both the data bus and the data parity bus as 2v signals during the MEM stage.
- A CPU stall occurs, so the next cycle is a STALL cycle instead of the normal WB cycle. In this case:
  - All signals driven during the initial MEM cycle are re-driven for all STALL cycles.
  - STALL cycles continue until the CPU deasserts STALLN.
- The CPU deasserts STALLN and the CPU pipeline proceeds to the WB stage.
Figure 4.8
CPU Load, Stall During MEM Stage

Phase 1 Phase 2
Phase 1 Phase 2 Phase 1 Phase 2

PCLKP

CDAP[31:0]

CDACCP[1:0]

CMDREQP

CSTREQP

OCMSELN

ODBREQP

CDATAP[31:0],
CDPARP[3:0]

STALLN

BENDNP

Note:
1. The signals shown with solid lines define the minimum required functionality. The section indicated by the dotted lines shows optional functionality.
CPU Store With a CPU Exception

- The CPU places the address for the on-chip memory on CDAP[31:0].
- The CPU sets CDACCP[1:0] to specify for the on-chip memory the data size for the store.
- The CPU asserts CMDREQP to validate the memory data address on the CDA bus.
- The CPU specifies the memory request direction by driving CSTREQP HIGH, requesting a store.
- The on-chip memory asserts OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The CPU asserts CDBREQP to notify the BIU that the CPU intends to drive both CDATAP[31:0] and CDPAR during the following MEM stage.
- An exception that occurs during the ALU stage causes the CPU to assert CMDRINVP as a 1s signal in the following MEM stage, notifying the on-chip memory to invalidate the memory data request.
  - Regardless of the exception, the CPU drives data on both the data bus and the data parity bus as 2v signals during the MEM stage.
  - The on-chip memory must not latch the presented CPU data.
- The CPU instruction pipeline continues execution.
Figure 4.9
CPU Store with an Exception During the ALU Stage

<table>
<thead>
<tr>
<th>Signal</th>
<th>Phase 1</th>
<th>Phase 2</th>
<th>Phase 1</th>
<th>Phase 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCLKP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDAP[31:0]</td>
<td></td>
<td>Data Address X</td>
<td>Address Y</td>
<td></td>
</tr>
<tr>
<td>CDACCP[1:0]</td>
<td></td>
<td>Access Type X</td>
<td>Access Type Y</td>
<td></td>
</tr>
<tr>
<td>CMDREQP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CSTREQP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>OCMSELP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDBREQP^1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CDATAP[31:0], CDPARP[3:0]</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CMDRINVP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BENDNP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note:
1. Internal signal shown for reference only.
CPU Store With an ALU-Stage Exception and a MEM-Stage Stall

- The CPU places the address for the on-chip memory on CDAP[31:0].
- The CPU sets CDACCP[1:0] to specify for the on-chip memory the data size for the store.
- CMDREQP validates the memory data address on the CDA bus.
- The CPU specifies the memory request direction by driving CSTREQP HIGH, requesting a store.
- The on-chip memory asserts OCMSELN to notify the BIU that the CPU memory request is for the on-chip memory, so the BIU should ignore the transaction.
- The CPU asserts CDBREQP to notify the BIU that the CPU intends to drive both CDATAP[31:0] and CDPARP[3:0] during the following MEM stage.
- An exception in the ALU stage causes the CPU to assert CMDRINVP as a 1s signal of the following MEM stage, notifying the on-chip memory to invalidate the memory data request.
- The CPU drives data on both the data bus and the data parity bus as 2v signals during the MEM stage. At the same time, a CPU stall occurs, so the next cycle is a STALL cycle instead of the normal WB cycle. In this case:
  - The on-chip memory must not latch the presented CPU data due to the assertion of CMDRINVP.
  - All signals driven during the initial MEM cycle, including the CPU data, are re-driven for all STALL cycles.
  - CMDRINVP must continue to inhibit the latching of CPU data by the on-chip memory for the duration of the STALL.
  - STALL cycles continue until STALLN is deasserted.
  - The CPU does not deassert CMDRINVP until after it deasserts STALLN.
- The CPU deasserts STALLN and the on-chip memory does not latch the CPU data because CMDRINVP is still asserted.
- The CPU deasserts CMDRINVP and the CPU pipeline proceeds to the WB stage.
4.4 Data Formats and Addressing

This section discusses the signals that define the data format and byte order for data operands in the CW33000. For additional information on required data formats and addressing, refer to Section 2.1, “Data and Registers,” of this document.

The signals that control data formats and addressing are:

- BENDNP
- CDACCP[1:0]
- CDAP[1:0]

The state of the BENDNP signal defines the endian byte ordering for the CW33000. External logic sets BENDNP during initialization and
BENDNP should not change during operation. If BENDNP equals one, the CW33000 utilizes a big-endian byte ordering where byte 0 (bits [31:24]) is the most significant byte of the word. Alternatively, if BENDNP equals zero, the CW33000 utilizes a little-endian byte ordering where byte 0 (bits [7:0]) is the least significant byte of the word.

The CW33000 CPU may load/store data items that consist of 32-bit words, 24-bit tribytes, 16-bit halfwords, and 8-bit bytes. Data transfer between the CPU and the on-chip memory, however, occurs in 32-bits words, although only part of each word may be valid. CDACCP[1:0], the data access type signals, specify the size of the valid data item for store operations only, according to Table 4.1.

<table>
<thead>
<tr>
<th>CDACCP[1:0]</th>
<th>Data Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>Byte</td>
</tr>
<tr>
<td>0 1</td>
<td>Halfword</td>
</tr>
<tr>
<td>1 0</td>
<td>Tribyte</td>
</tr>
<tr>
<td>1 1</td>
<td>Word</td>
</tr>
</tbody>
</table>

CDAP[1:0], the two least significant bits of the CPU Data Address bus, specify the location of the valid byte(s) within the 32-bit data word. In particular, these bits specify the valid byte that has the smallest byte address in the addressed field.

CDACCP[1:0] and CDAP[1:0] together encode which bytes within the addressed word are to be written during a CP Store Byte operation, as illustrated in Figure 4.11. These control signals should also generate the appropriate byte write enable signal while the entire word is addressed, that is when CDAP[1:0] = (0,0).

For CPU Load Byte operations, all 32 bits of the on-chip memory's addressed word should be presented to the CPU independent of these control signals, again when CDAP[1:0] = (0,0). The CPU handles byte selection according to the CPU load byte instruction being executed.
Figure 4.11
Byte Specifications for Loads/Stores

<table>
<thead>
<tr>
<th>Access Type (CDACCP[1:0])</th>
<th>Low-Order Address Bits: CDA1 CDA0</th>
<th>Bytes Accessed</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>31</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Big-Endian (BENDNP = 1)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Little-Endian (BENDNP = 0)</td>
</tr>
<tr>
<td>Word (1,1)</td>
<td>0 0</td>
<td>0 1 2 3</td>
</tr>
<tr>
<td>Tribyte (1,0)</td>
<td>0 0</td>
<td>0 1 2 3</td>
</tr>
<tr>
<td></td>
<td>0 1</td>
<td>1 2 3</td>
</tr>
<tr>
<td>Halfword (0,1)</td>
<td>0 0</td>
<td>0 1 2 3</td>
</tr>
<tr>
<td></td>
<td>1 0</td>
<td>1 2 3</td>
</tr>
<tr>
<td>Byte (0,0)</td>
<td>0 0</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>0 1</td>
<td>0 1</td>
</tr>
<tr>
<td></td>
<td>1 0</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>1 1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3</td>
</tr>
</tbody>
</table>

Direct CPU Data Bus Interface
Chapter 5
I/O Interface Operation

This chapter contains waveforms that depict the CW33000’s I/O functions as they appear at its interfaces. The waveforms illustrate both how the CW33000’s signals interrelate and how operations initiated on one interface propagate to other interfaces.

The chapter is divided into the following sections that describe different types of memory transactions:

- Interpreting the Waveforms
- Word Read Transactions
- Block-Fetch Transactions
- Write Transactions
- Byte-Gathering Transactions
- Automatic Wait-State Generation
- Bus Errors

5.1 Interpreting the Waveforms

This chapter uses the following conventions for annotating illustrations and discussing waveforms in text:

- Addresses: Addresses are represented by the letter “A” and a number, where the number differentiates between addresses in the waveform. An X represents a don’t care address value.

- Data and Instructions: The data being transferred in an operation are represented by the letter “D” and a number, where the number identifies the address with which the data are associated. An X represents a don’t care data value.

- Data Parity: The parity associated with a data transfer is represented by the letter “P” and a number, where the number identifies the parity with the data with which it is associated.
For the sake of clarity, some CW33000 signals are not included in these illustrations. You may assume that these signals are deasserted for the duration of the operation.

5.2 Word Read Transactions

The most basic memory transaction is a word read, which is a transfer of data from an external memory system to the CW33000. A read transaction consists of four distinct states, as shown in Figure 5.1 and described below:

State 1. At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. The CW33000 also asserts BFREQOP, if appropriate.

State 2. The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid, and it asserts RDON to indicate that the memory system can put data on DIP[31:0].

State 3. At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, CACHDN, and BFTCHN. If DRDYN and/or BERRN are asserted, the CW33000 progresses to State 4. If neither is asserted, the CW33000 makes the current cycle a wait cycle. The CW33000 continues to sample DRDYN and BERRN until the memory system asserts one or both.

State 4. At the rising edge of PCLKP, the CW33000 samples DIP[31:0] and DPIP[3:0]. The CW33000 drives the current instruction address onto AOP[31:0] and deasserts RDON, ASON, and BFREQOP.
Figure 5.1
Word Read Transaction
5.3 Block-Fetch Transactions

A block-fetch transaction allows the CW33000 to fill its cache memories quickly. A block-fetch transaction is similar to a read transaction, but transfers a series of two to 16 words from memory to the CW33000. A 16-word block-fetch transaction is shown in Figure 5.2 and described below:

State 1. At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. The CW33000 also asserts BFREQOP to indicate that a block-fetch transaction is desired.

State 2. The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid, and it asserts RDON to indicate that the memory system can put data on DIP[31:0].

Wait. At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, CACHDN, and BFTCHN. The memory system asserts BFTCHN to indicate that the current transaction is a block fetch. The assertion of BFTCHN causes the CW33000 to set the block address, AOP[5:2] (modulo the block size), to zero. BFTCHN must remain asserted for the duration of the block-fetch transaction.

Because this transaction is a block fetch, the memory system must cause at least one wait state in this part of the transaction and so does not assert DRDYN. The CW33000 continues to sample DRDYN and BERRN until the memory system asserts one or both. When the memory system asserts DRDYN in the second half of the wait state, the CW33000 advances to State 3.

State 3. During the first transfer, the CW33000 samples CACHDN and PENN. CACHDN must be asserted; asserting PENN is optional. The memory system can insert a wait state for any cycle by deasserting DRDYN before the CW33000 samples it at the falling edge of PCLKP in State 3. If DRDYN is not asserted, the CW33000 does not increment the address in State 4.

State 4. At the rising edge of PCLKP, the CW33000 samples DIP[31:0] and DPIP[3:0] and increments the block address.

States 3 and 4 repeat until the block count reaches zero or a bus error occurs. When the block count reaches zero, the CW33000 ends the block transfer by deasserting ASON and RDON. The memory system deasserts DRDYN.
The CW33000 automatically caches instructions or data (if the system includes a D-cache) fetched during a block fetch transaction regardless of the state of the CACHDN signal. Refer to Section 2.5, "Cache Operation," for more information about cache operation during block fetch transactions.
5.4 Write Transactions

A write transaction is a transfer of data from the CW33000 to an external memory system. Like a word read, a write consists of four distinct states, shown in Figure 5.3 and described below:

State 1. At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. The CW33000 also deasserts RTON to indicate that the current transaction is a write, and it deasserts RDON to indicate that the memory system must not drive data on DIP[31:0].
State 2. The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid.

State 3. The CW33000 drives the write data onto DOP[31:0] and DPOP[3:0]. It also asserts WRN[3:0] for each valid byte of data on DOP[31:0]. The CW33000 deasserts MXSN.

At the falling edge of PCLKP, the CW33000 samples DRDYN and BERRN. If DRDYN and/or BERRN is asserted, the CW33000 progresses to State 4. If neither is asserted, the CW33000 makes the current cycle a wait cycle. The CW33000 continues to sample DRDYN and BERRN until the memory system asserts one or both.

State 4. The memory system samples DOP[31:0] and DPOP[3:0]. At the end of this state, the CW33000 deasserts ASON, WRN[3:0], DOP[31:0], and DPOP[3:0].
Figure 5.3
Write Transaction

I/O Interface Operation
5.5 Byte-Gathering Transactions

To support byte-wide devices better, the CW33000 performs byte gathering, which appears on the memory interface as a series of four single-byte memory transactions. A read transaction consists of four distinct states as shown in Figure 5.4 and described below:

State 1. At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. The CW33000 also asserts BFREQOP, if appropriate.

State 2. The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid, and it asserts RDON to indicate that the memory system can put data on DIP[31:0].

Wait. At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, CACHDN, BFTCHN, and BWIDEN. The assertion of BWIDEN causes the CW33000 to perform byte gathering, starting with the addressed byte.

Because the PROM in this example is too slow to provide single-cycle access, the memory system does not assert DRDYN and so causes a wait state. The CW33000 continues to sample DRDYN and BERRN until the memory system asserts one or both. When the memory system asserts DRDYN in the second half of the wait state, the CW33000 advances to State 3.

State 3. The CW33000 samples DRDYN, PENN, BERRN, CACHDN, and BFTCHN. When DRDYN and/or BERRN are asserted, the CW33000 progresses to State 4.

State 4. At the rising edge of PCLKP, the CW33000 samples DIP[31:0] and DPIP[3:0].

The four states described above are repeated four times, once for each byte, or until a bus error occurs. Note that the byte address increments by one for each transaction.

Note

External logic indicates a bus error during a byte-gathering transaction the same way it indicates a bus error during a word read transaction. If a bus error occurs during a byte-gathering transaction, external logic must assert BERRN during the first byte-gathering transaction only. It must not assert BERRN during the second, third, or fourth byte-gathering transactions.
Figure 5.4
Byte Gathering Transactions
(Sheet 2 of 2)
5.6 Automatic Wait-State Generation

To accommodate devices of varying access times, the BIU incorporates a wait-state generator for both the IOSELN and EPSELN address spaces. When either wait-state generator is enabled, the BIU latches the contents of the data bus a programmable number of clock cycles after the start of the memory transaction (as signaled by the assertion of MXSN). When the wait-state generators are enabled, the addressed device need not assert DRDYN to end the transaction. However, the addressed device may end the transaction before the wait-state count expires by asserting DRDYN. This feature allows devices of different speeds to be connected in the same address space; faster devices may end the transaction before the wait-state count expires. Note that the wait-state generators do not support block fetching.

Configuration

The wait-state generators are enabled and programmed via four fields in the Configuration Register, highlighted in the diagram below. Software can read and write the Configuration Register at address 0xFFFE.0020. These four fields have the following definitions:

<table>
<thead>
<tr>
<th>Location: Memory</th>
<th>Cold Reset Initial Value: 0x0001.EF28</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address: 0xFFFE.0020</td>
<td>Warm Reset Initial Value: Unchanged</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>31</th>
<th>24</th>
<th>23</th>
<th>22</th>
<th>21</th>
<th>20</th>
<th>19</th>
<th>18</th>
<th>17</th>
<th>16</th>
<th>15</th>
<th>14</th>
<th>13</th>
<th>12</th>
<th>11</th>
<th>10</th>
<th>9</th>
<th>8</th>
<th>7</th>
<th>6</th>
<th>5</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reserved</td>
<td>ICD</td>
<td>DCD</td>
<td>IBS</td>
<td>DBS</td>
<td>IW</td>
<td>IOWAIT</td>
<td>PW</td>
<td>PWAIT</td>
<td>CS</td>
<td>PE</td>
<td>RG</td>
<td>BFD</td>
<td>RGN</td>
<td>RPC</td>
<td>CL</td>
<td>DCE</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

IW

**IOSELN Wait Disable**

When set to one, IW disables the IOSELN Wait feature. When the IOSELN Wait feature is disabled, the CW33000 asserts IOSELN during IOSELN space accesses and waits until the accessed device asserts DRDYN before ending the memory transaction. When IW is set to zero, the CW33000 ends the memory cycle either after waiting the number of clock cycles defined by the IOWAIT field or when the external device asserts DRDYN.

IOWAIT

**IOSELN Wait**

The four-bit IOWAIT field defines the number of clock cycles that the CW33000 waits before ending a memory transaction in the IOSELN address space. The valid range for IOWAIT is from 0 to 15 cycles.

PW

**EPSELN Wait Disable**

When set to one, PW disables the EPSELN Wait feature. When the EPSELN Wait feature is disabled, the CW33000 asserts EPSELN.
during EPSELN space accesses and waits until the PROM asserts DRDYN before ending the memory transaction. When PW is set to zero, the CW33000 ends the memory cycle either after waiting the number of clock cycles defined by the PWAIT field or when the external device asserts DRDYN.

<table>
<thead>
<tr>
<th>PWAIT</th>
<th>EPSELN Wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>[11:8]</td>
<td>The four-bit PWAIT field defines the number of clock cycles that the CW33000 will wait before ending a memory transaction in the EPSELN address space. The valid range for PWAIT is from 0 to 15 cycles.</td>
</tr>
</tbody>
</table>

A read transaction with five wait states is shown in Figure 5.5 and described below:

State 1. At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. Block-fetch transactions are not supported in the IOSELN and EPSELN address spaces when the wait-state generator is enabled.

State 2. The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid, and it asserts RDON to indicate that the memory system can put data on DIP[31:0].

Wait. At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, and CACHDN. Because the wait-state generator for the EPSELN address space is enabled, the CW33000 begins automatically generating wait states. When the wait-state count expires, the CW33000 advances to State 3. The memory system can assert DRDYN before the wait-state count expires and end the transaction early if desired.

State 3. The CW33000 samples PENN, BERRN, and CACHDN. The CW33000 progresses to State 4.

State 4. At the rising edge of PCLKP, the CW33000 samples DIP[31:0] and DPIP[3:0].
Figure 5.5
Automatic Wait-State Generation

<table>
<thead>
<tr>
<th>PCLKP</th>
<th>S1</th>
<th>S2</th>
<th>W</th>
<th>W</th>
<th>W</th>
<th>W</th>
<th>W</th>
<th>W</th>
<th>S3</th>
<th>S4</th>
</tr>
</thead>
<tbody>
<tr>
<td>AOP[31:0]</td>
<td></td>
<td></td>
<td>A0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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</tr>
<tr>
<td>DIP[31:0]</td>
<td></td>
<td></td>
<td></td>
<td>D0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>DPIP[3:0]</td>
<td></td>
<td></td>
<td>P0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
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<tr>
<td>MXSN</td>
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<td>DRDYN</td>
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<td></td>
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<td></td>
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<tr>
<td>RDON</td>
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<td></td>
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<td></td>
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<td></td>
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</tr>
<tr>
<td>ASON</td>
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<td></td>
<td></td>
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<td></td>
<td></td>
<td></td>
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<tr>
<td>RTON</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>WRN[3:0]</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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</tr>
<tr>
<td>BFREQOP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>BFTCHN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>DTON</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

I/O Interface Operation
## 5.7 Bus Errors

If the target of a memory access detects an error during the transaction, it signals the error by asserting BERRN. Asserting BERRN terminates the transaction and causes the CW33000 to execute a Bus Error Exception.

### Read Transactions

In response to bus errors during read transactions, the CW33000 terminates transactions gracefully. If a bus error occurs during a byte-gathering operation, the CW33000 terminates the current memory transaction and any transactions that would be required to complete the byte-gathering operation. If a bus error occurs during a block-fetch transaction, the CW33000 terminates the current memory transaction and any transactions that would be required to complete the block fetch.

Figure 5.6 illustrates a bus error during a block-fetch transaction. The transaction is described below:

**State 1.** At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. The CW33000 also asserts BFREQOP to indicate that a block-fetch transaction is desired.

**State 2.** The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid, and it asserts RDON to indicate that the memory system can put data on DIP[31:0].

**Wait.** At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, CACHDN, and BFTCHN. The memory system asserts BFTCHN to indicate that the current transaction is a block fetch. The assertion of BFTCHN causes the CW33000 to set the block address, AOP[5:3] modulo the block size, to zero.

Because this transaction is a block fetch, the memory system must cause a wait state in this cycle and so does not assert DRDYN. The CW33000 continues to sample DRDYN and BERRN until the memory system asserts one or both. When the memory system asserts DRDYN in the second half of the wait state, the CW33000 advances to State 3.

**State 3.** During the first transfer, the CW33000 samples CACHDN and PENN. CACHDN must be asserted, because the memory access is a block-fetch transaction; asserting PENN is optional. The memory system can insert a wait state for any cycle by
deasserting DRDYN before the CW33000 samples it at the falling edge of PCLKP in State 3. If DRDYN is not asserted, the CW33000 does not increment the address in State 4.

State 4. At the rising edge of PCLKP, the CW33000 samples DIP[31:0] and DPIP[3:0] and increments the block address.

Wait. At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, CACHDN, and BFTCHN. Because the DRAM in this example is too slow to provide single-cycle access, the memory system does not assert DRDYN and so causes a wait state. When the memory system asserts DRDYN in the second half of the wait state, the CW33000 advances to State 3.

State 3. The memory system asserts BERRN to indicate that it cannot complete the block-fetch transaction. At the falling edge of PCLKP, the CW33000 samples DRDYN, PENN, BERRN, CACHDN, and BFTCHN and detects the error.

State 4. The CW33000 deasserts ASON and RDON.

Note External logic must assert BERRN until after the CW33000 deasserts ASON.
Figure 5.6
Bus Error During a Block-Fetch Transaction
Figure 5.3 illustrates a bus error during a write transaction. The transaction is described below:

State 1. At the rising edge of PCLKP, the CW33000 drives the address onto AOP[31:0] and asserts MXSN to indicate the start of a memory transaction. The CW33000 also asserts deasserts RTON to indicate that the current transaction is a write, and it deasserts RDON to indicate that the memory system must not drive data on DIP[31:0].

State 2. The CW33000 asserts ASON to indicate that the address on AOP[31:0] is valid.

State 3. At the rising edge of PCLKP, the CW33000 drives the write data onto DOP[31:0] and DPOP[3:0]. It also asserts WRN[3:0] for each valid byte of data on DOP[31:0]. The CW33000 deasserts MXSN.

At the falling edge of PCLKP, the CW33000 samples DRDYN and BERRN. Because both DRDYN and BERRN are asserted, the CW33000 terminates the transaction and executes a Bus Error Exception.

State 4. At the rising edge of PCLKP, the CW33000 deasserts AOP[31:0], WRN[3:0], and ASON. The transaction ends.

If a bus error occurs during a write transaction, the memory system should not complete a transaction by latching data. Memory state should not be affected by write transactions that terminate with bus errors.
Figure 5.7
Bus Error During a Write Transaction
Chapter 6
AC Specifications

This chapter provides the AC specifications for the LSI Logic CW33000 MIPS Embedded Processor building block, including the AC timing as well as input and output loading and drive type information.

6.1 AC Timing

This section describes the AC timing characteristics of the CW33000's memory interface, including the Direct CPU Data Bus Interface to a user-designed on-chip memory. The timing relationships between PCLKP and various CW33000 signals that comprise its memory interface are depicted in Figures 6.1 through 6.22. The figures depict:

- Clock Timing (Figure 6.1)
- Cold Reset Timing (Figure 6.2)
- Warm Reset Timing (Figure 6.3)
- Three-State Enable Control Timing (Figure 6.4)
- Read Transaction Timing (Figure 6.5)
- Write Transaction Timing (Figure 6.6)
- Block-Fetch Transaction Timing (Figure 6.7)
- Synchronous Bus Arbitration Timing (Figure 6.8)
- Bus Snooping Timing (Figure 6.9)
- DRAM Read Timing (Figure 6.10)
- DRAM Write Timing (Figure 6.11)
- DRAM Block-Fetch Timing (Figure 6.12)
- DRAM Refresh Timing (Figure 6.13)
- DMA Access Timing Using BGNTP (Figure 6.14)
- DMA Access Timing Using DMARN (Figure 6.15)
- Timing for Miscellaneous Input and Output Signals (Figure 6.16)
- DCDBI Timing for a CPU Store (Figure 6.17)
- DCDBI Timing for a CPU Load (Figure 6.18)
- Data Cache Data Read Timing (Figure 6.19)
- Data Cache Tag and Valid Bit Read Timing (Figure 6.20)
- Data Cache Data Write Timing (Figure 6.21)
- Data Cache Tag and Valid Bit Write Timing (Figure 6.22)

The numbers in Figures 6.1 through 6.22 refer to the timing parameters listed in column 1 of Table 6.1. All of the timing parameters are valid for worst case commercial (WCCOM) die conditions as specified for the LSI Logic LCB007 process. Note that the AC timing is valid only when the customer-designed peripheral logic does not exceed the customer loading numbers provided and discussed in Section 6.2.
Figure 6.3
Warm Reset Timing

Note:
1. Parameters 115 and 116 are provided for designers who need to synchronize the CW33000's RESETN or HIGHZN state with other devices. These parameters can be ignored for asynchronous applications.

Figure 6.4
Three-State Enable Control Timing

Note:
1. Parameters 11a and 11b are provided for designers who need to synchronize the CW33000's RESETN or HIGHZN state with other devices. These parameters can be ignored for asynchronous applications.
Figure 6.5
Read Transaction Timing
Figure 6.6
Write Transaction Timing

- PCLKP
- AOP[31:0]
- BFREQOP
- MXSN
- ASON
- WRN[3:0]
- RTON
- DRDYN
- BERRN
- DTON
- EPSELN
- IOSELN
- DOP[31:0]
- DPOP[3:0]
- DBENN
Figure 6.7
Block-Fetch Transaction Timing

Note:
1. This waveform depicts a two-word block fetch. As shown in the waveform, the address increments three times for this two-word fetch. The memory system should ignore the final address in a block fetch of any length. For larger block fetches, States 3 and 4 repeat until the fetch is complete. The memory system may insert wait states in between States 4 and 3.
Figure 6.8
Synchronous Bus Arbitration Timing

Notes:
1. OBENN is the enable control signal for OOP[31:0] and OPOP[3:0].
2. BIDENN is the enable control signal for AOP[31:0], ASON, RDON, WRN[3:0], MXSN, RTON, BFREQOP, and DTON.

Figure 6.9
Bus Snooping Timing

Note:
1. There may be any number of cycles between assertion of BGNTP and assertion of ASIN for the purposes of bus snooping.
Figure 6.10
DRAM Read Timing

AC Specifications
Figure 6.12
DRAM Block-Fetch Timing

PCLKP

AOP[31:0]

MXSN

BFREQOP

DRASN

DCASN

DMXSP

DOEN

DIP[31:0]

DPIP[3:0]
Figure 6.13
DRAM Refresh Timing

Figure 6.14
DMA Access Timing Using BGNTP

Notes:
1. The external master must assert ASIN until the Controller asserts DRASN (but not RTMOUTN).
2. When an n-word block fetch takes place, the DCASN that corresponds to the nth word (page-mode DRAM access) marks the end of the transaction.
3. There may be any number of cycles between the assertion of BGNTP and the assertion of ASIN for the purpose of starting the DRAM Controller's access.
Figure 6.15
DMA Access Timing Using DMARN

Note:
1. DMARN is an asynchronous signal. DMARN may be deasserted at any time, once the pulse width is satisfied. DMARN must be deasserted and then reasserted to initiate another DMACN sequence.

Figure 6.16
Timing for Miscellaneous Input and Output Signals
Figure 6.17
DCDBI Timing for a CPU Store

Note:
1. Internal signal shown for reference only.
Figure 6.18
DCDBI Timing for a CPU Load

RUN (ALU Stage)
Phase 1
Phase 2
Data Address X
Address X
Access Type X
Access Type Y

RUN (MEM Stage)
Phase 1
Phase 2
Address Y
Access Type Y

STALL Cycle
Phase 1
Phase 2

PCLKP
CDAP[31:0]
CDACCP[1:0]
CMDREQP
CSTREQP
OCMSELN
ODBREQP
CDATAP[31:0], CDPAR[3:0]
STALLN
BENDNP

RUN (MEM Stage)

AC Specifications
Figure 6.19
Data Cache Data Read Timing

Figure 6.20
Data Cache Tag and Valid Bit Read Timing
<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
<th>25 MHz</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Min</td>
</tr>
<tr>
<td>1. t\text{SH}</td>
<td>PCLKP High (&gt;1.5 V)</td>
<td>18</td>
</tr>
<tr>
<td>2. t\text{SL}</td>
<td>PCLKP Low (&lt;1.5 V)</td>
<td>18</td>
</tr>
<tr>
<td>3. t\text{SF}</td>
<td>PCLKP Fall (transition)</td>
<td>–</td>
</tr>
<tr>
<td>4. t\text{SR}</td>
<td>PCLKP Rise (transition)</td>
<td>–</td>
</tr>
<tr>
<td>5. t\text{SCYC}</td>
<td>PCLKP cycle</td>
<td>40</td>
</tr>
<tr>
<td>6. t\text{VRL}</td>
<td>VDD (≥3.0 V) to RESETN Low</td>
<td>–</td>
</tr>
<tr>
<td>7. t\text{VHZL}</td>
<td>VDD (≥3.0 V) to HIGHZN Low</td>
<td>–</td>
</tr>
<tr>
<td>8. t\text{RLC}</td>
<td>RESETN Low (Cold)$^1$</td>
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</tr>
<tr>
<td>9. t\text{RHZH}</td>
<td>RESETN High to HIGHZN High (Cold)$^1$</td>
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<td>10. t\text{RLW}</td>
<td>RESETN Low (Warm)$^1$</td>
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<td>11a. t\text{HZSC}</td>
<td>HIGHZN Setup before PCLKP+</td>
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<tr>
<td>11b. t\text{HZHC}</td>
<td>HIGHZN Hold from PCLKP+</td>
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</tr>
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<td>11c. t\text{HZNM}</td>
<td>HIGHZN- to BIDENN-, DBENN-, HIGHZIOP-, BHIGHZN+</td>
<td>–</td>
</tr>
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<td>11d. t\text{HZPM}</td>
<td>HIGHZN+ to BIDENN+, DBENN+, HIGHZIOP+, BHIGHZN-</td>
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<tr>
<td>13. t\text{SHAV}</td>
<td>PCLKP+ to Address Valid</td>
<td>–</td>
</tr>
<tr>
<td>14. t\text{SHBRV}</td>
<td>PCLKP+ to BFREQOP Valid$^2$</td>
<td>–</td>
</tr>
<tr>
<td>15. t\text{SHBRI}</td>
<td>PCLKP+ to BFREQOP Invalid</td>
<td>–</td>
</tr>
<tr>
<td>16. t\text{SHML}</td>
<td>PCLKP+ to MXSN Low</td>
<td>–</td>
</tr>
<tr>
<td>17. t\text{SHRIL}</td>
<td>PCLKP+ to RTON Low</td>
<td>–</td>
</tr>
<tr>
<td>18. t\text{SHRTH}</td>
<td>PCLKP+ to RTON High</td>
<td>–</td>
</tr>
<tr>
<td>19. t\text{SHDTV}</td>
<td>PCLKP+ to DTON Valid</td>
<td>–</td>
</tr>
<tr>
<td>20. t\text{SHDTI}</td>
<td>PCLKP+ to DTON Invalid</td>
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</tr>
<tr>
<td>21. t\text{SLAL}</td>
<td>PCLKP- to ASON, RDON Low</td>
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</tr>
<tr>
<td>22. t\text{SLSL}</td>
<td>PCLKP- to IOSELN or EPSELN Low</td>
<td>–</td>
</tr>
<tr>
<td>23. t\text{SLSH}</td>
<td>PCLKP+ to IOSELN or EPSELN High</td>
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<td>24. t\text{AVISL}</td>
<td>Address Valid to ASON, RDON, IOSELN, EPSELN Low</td>
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<tr>
<td>25. t\text{CSSL}</td>
<td>Control$^3$, Setup to PCLKP-</td>
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<tr>
<td>26. t\text{CHSL}</td>
<td>Cонтrol$^4$, Hold from PCLKP-</td>
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<tr>
<td>26a. t\text{BEHSL}</td>
<td>BERNH Hold from PCLKP-</td>
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<tr>
<td>27. t\text{DSSH}</td>
<td>Data and Parity Setup before PCLKP+</td>
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(Sheet 1 of 4)
<table>
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<th>Max</th>
<th>Units</th>
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<td>Data and Parity Hold from PCLKP+</td>
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<td>ns</td>
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<tr>
<td>29. tSHASH</td>
<td>PCLKP+ to ASON, RDON High</td>
<td>–</td>
<td>8</td>
<td>ns</td>
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<td>30. tAHSH</td>
<td>Address Hold from ASON, RDON, IOSELN, EPSELN</td>
<td>1</td>
<td>–</td>
<td>ns</td>
</tr>
<tr>
<td>30a. tAHWH</td>
<td>Address Hold from WRN[3:0] High</td>
<td>0</td>
<td>–</td>
<td>ns</td>
</tr>
<tr>
<td>31. tSHWRV</td>
<td>PCLKP+ to WRN[3:0] Valid</td>
<td>–</td>
<td>6</td>
<td>ns</td>
</tr>
<tr>
<td>32. tSHDV</td>
<td>PCLKP+ to Data and Parity Valid</td>
<td>–</td>
<td>17</td>
<td>ns</td>
</tr>
<tr>
<td>33. tSHWRH</td>
<td>PCLKP+ to WRN[3:0] High</td>
<td>–</td>
<td>6</td>
<td>ns</td>
</tr>
<tr>
<td>34. tWRHDI</td>
<td>WRN[3:0] High to Data and parity invalid</td>
<td>6</td>
<td>–</td>
<td>ns</td>
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<td>35. tBFSSL</td>
<td>BFTCHN Setup to PCLKP.</td>
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<td>ns</td>
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<td>36. tBFHSL</td>
<td>BFTCHN Hold from PCLKP-</td>
<td>0</td>
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<td>ns</td>
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<td>37. tSLBAV</td>
<td>PCLKP- to Block Address</td>
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<td>38. tBHZBGH</td>
<td>Bus Signal Enables to BGNTP High</td>
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<td>38a. tBABGL</td>
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<td>ns</td>
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<td>39. tBSSH</td>
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<td>–</td>
<td>ns</td>
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<td>PCLKP- to BGNTP High</td>
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<td>11</td>
<td>ns</td>
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<td>41. tBHSH</td>
<td>BREQN Hold after PCLKP+</td>
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<td>–</td>
<td>ns</td>
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<td>42. tSLBGL</td>
<td>PCLKP- to BGNTP Low</td>
<td>–</td>
<td>11</td>
<td>ns</td>
</tr>
<tr>
<td>43. tBGHSL</td>
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<td>ns</td>
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<tr>
<td>44. tRTVASL</td>
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<td>ns</td>
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<td>45. tCAVASL</td>
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<td>ns</td>
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<td>46. tASSSH</td>
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<td>–</td>
<td>ns</td>
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<td>47. tASHSH</td>
<td>ASIN, RTIN, CACHDN Hold from PCLKP+</td>
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<td>ns</td>
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<td>48. tASSL</td>
<td>Address Setup to PCLKP-</td>
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<td>ns</td>
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<td>49. tAHSL</td>
<td>Address Hold from PCLKP-</td>
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<td>ns</td>
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<td>51. tSLRL</td>
<td>PCLKP- to DRASN Low</td>
<td>–</td>
<td>9</td>
<td>ns</td>
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<tr>
<td>53. tASRL</td>
<td>Address Setup to DRASN Low</td>
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<td>ns</td>
</tr>
<tr>
<td>54. tSLMSL</td>
<td>PCLKP- to DMXSP Low</td>
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<tr>
<td>55. tSLMSH</td>
<td>PCLKP- to DMXSP High</td>
<td>–</td>
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<tr>
<td>56. tSLCAL</td>
<td>PCLKP+/– to DCASN Low</td>
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<tr>
<td>57. tSLOEL</td>
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<td>25 MHz Max</td>
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<td>60. t\textsubscript{CAPW}</td>
<td>DCASN Precharge Time</td>
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<td>61. t\textsubscript{SLRTOV}</td>
<td>PCLKP- to RTMOUTN Valid</td>
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<tr>
<td>62. t\textsubscript{SLRTOI}</td>
<td>PCLKP- to RTMOUTN Invalid</td>
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<td>63. t\textsubscript{SLRAH}</td>
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<td>64a. t\textsubscript{ASASL}</td>
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<td>64b. t\textsubscript{AHASH}</td>
<td>Address Hold from ASIN High</td>
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<td>65. t\textsubscript{CSAL}</td>
<td>RDIN, BFREQP, and DTIN Setup to ASIN Low</td>
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<td>–</td>
<td>ns</td>
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<td>66. t\textsubscript{CHSH}</td>
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<td>ns</td>
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<td>68. t\textsubscript{SLDMCV}</td>
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<td>69. t\textsubscript{SLDMCI}</td>
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<td>70. t\textsubscript{CADDT}</td>
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<td>71. t\textsubscript{CADTV}</td>
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<td>72. t\textsubscript{CSSD}</td>
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<td>77. t\textsubscript{DITSC}</td>
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<td>78. t\textsubscript{DITHC}</td>
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<td>79. t\textsubscript{DIVSC}</td>
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<td>80. t\textsubscript{DIVHC}</td>
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<td>81. t\textsubscript{CWDTV}</td>
<td>PCLKP+ to WEDATP[3:0], WETAGP, WEVALP[3:0] High and PCLKP+ to WEDATP[3:0], WETAGP, WEVALP[3:0] Low</td>
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<td>82. t\textsubscript{CDOD}</td>
<td>PCLKP+ to CDATAP[31:0]</td>
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<td>83. t\textsubscript{CCDA}</td>
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<td>84. t\textsubscript{CCDAC}</td>
<td>PCLKP+ to CDACC[1:0] Active or Inactive</td>
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<th>Units</th>
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<td>OCMSELN Hold from PCLKP+</td>
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<td>88. ( t_{CDSC} )</td>
<td>CDATAP[31:0], CDPARP[3:0] Setup to PCLKP+</td>
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<tr>
<td>89. ( t_{CDAC} )</td>
<td>CDATAP[31:0], CDPARP[3:0] Hold from PCLKP+</td>
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<tr>
<td>90. ( t_{CCSTL} )</td>
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<tr>
<td>91. ( t_{CSTH} )</td>
<td>PCLKP- to STALLN High</td>
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<tr>
<td>92. ( t_{CCMD} )</td>
<td>PCLKP- to CMDRINVP High or Low</td>
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<td>93. ( t_{ODBSC} )</td>
<td>ODBREQP Setup to PCLKP+</td>
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<tr>
<td>94. ( t_{ODPHC} )</td>
<td>ODBREQP Hold from PCLKP+</td>
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<tr>
<td>95. ( t_{CPDP} )</td>
<td>PCLKP+ to CDATAP[31:0], CDPARP[3:0]</td>
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<td>96. ( t_{CNBV} )</td>
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<tr>
<td>103. ( t_{FSSL} )</td>
<td>FRCMN Setup to PCLKP-</td>
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<td>104. ( t_{FISH} )</td>
<td>FRCMN Hold from PCLKP+</td>
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<td>– ns</td>
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<td>105. ( t_{RSSH} )</td>
<td>Miscellaneous Synchronous Setup to PCLKP+</td>
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<td>106a. ( t_{TISH} )</td>
<td>T2EN Hold from PCLKP+</td>
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<td>– ns</td>
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<td>107. ( t_{FSSL} )</td>
<td>INTP[5:0] Setup to PCLKP-</td>
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<td>108. ( t_{FISH} )</td>
<td>INTP[5:0] Hold from PCLKP-</td>
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<td>109a. ( t_{CPPV} )</td>
<td>PCLKP+ to PERRP Valid</td>
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<tr>
<td>109b. ( t_{CPTV} )</td>
<td>PCLKP+ to T2TOP Valid</td>
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<td>9 ns</td>
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<tr>
<td>111. ( t_{ASPW} )</td>
<td>ASIN Pulse Width</td>
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<td>– Cycle</td>
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<td>115. ( t_{RSCP} )</td>
<td>RESETN Setup to PCLKP+</td>
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<td>– ns</td>
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<td>116. ( t_{RSCN} )</td>
<td>RESETN Hold from PCLKP+</td>
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<td>– ns</td>
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<tr>
<td>117. ( t_{SHDBV} )</td>
<td>PCLKP+ to DBENN Valid</td>
<td>–</td>
<td>6 ns</td>
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<tr>
<td>118. ( t_{SHDBI} )</td>
<td>PCLKP+ to DBENN Invalid</td>
<td>–</td>
<td>8 ns</td>
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</tbody>
</table>

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1. PCLKP must be active for RESETN to take effect.
2. Block-fetch transactions must have one wait state in the first word of a block fetch. A block-fetch transaction is requested on any read access to cacheable memory after a cache miss.
3. These control signals include DRDYN, BERN, CACHDN, BWIDEN, and PENN. To prevent affecting the next transaction, these signals should be deasserted within 1.5 system clock cycles of PCLKP-.

4. Once sampled at PCLKP-, BWIDEN is ignored until four bytes have been fetched or a bus error has been detected. PENN is ignored if BWIDEN is sampled at PCLKP-.

5. These control signals include DRDYN, CACHDN, BWIDEN, and PENN.

6. To prevent affecting the next transaction, BFTCHN should be deasserted within 1.5 system clock cycles of PCLKP-.

7. Block address 0 is placed on the address bus in response to BFTCHN LOW. Each subsequent address is issued in response to DRDYN LOW. ASON and RDON are deasserted after all data in a block have been fetched or a bus error occurs.

8. Cache invalidation occurs when RTIN is deasserted and CACHDN is asserted.

9. Miscellaneous synchronous signals include CPCP[3:0], RTACKP, and T2ENP.

10. Miscellaneous synchronous signals include CPCP[3:0] and RTACKP.

6.2 Loading Information

This section provides specific loading information for the CW33000 inputs and loading and drive type information for the outputs. It also provides loading information for the customer-designed peripheral logic. The section is organized this way:

- Input Loading
- Output Loading and Driver Type
- Customer Output Loading

Table 6.2 lists the total number of equivalent standard loads and total capacitive load presented by the CW33000 inputs to the customer-designed peripheral logic. Note that the number of equivalent standard loads represents contributions from both the fan-in and the wire in the CW33000. Also, capacitive load numbers assume 0.0784 pF per standard load (for the LSI Logic LCB007 process), and both the number of standard loads and the total capacitive load values are rounded off.
<table>
<thead>
<tr>
<th>Signal Name</th>
<th>Number of Standard Loads</th>
<th>Total Capacitive Load (pF)</th>
<th>Signal Name</th>
<th>Number of Standard Loads</th>
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(Sheet 2 of 3)
Table 6.2 (Continued)

CW33000 Input Loading

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<th>Signal Name</th>
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Table 6.3 provides the output loading values for the CW33000. These values represent the load presented looking back into the CW33000 outputs. Note that the number of equivalent standard loads represents contributions from both the fan-out and the wire in the CW33000. Also, capacitive load numbers assume 0.0784 pF per standard load (for the LSI Logic LCB007 process), and both the number of standard loads and the total capacitive load values are rounded off. Table 6.4 lists the driver type for each of the outputs.

Table 6.3

CW33000 Output Loading

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<th>Signal Name</th>
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CW33000 Output Loading

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CW33000 Output Loading

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(Sheet 4 of 4)

AC Specifications 6-27
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Table 6.5 lists the assumed customer loading on the CW33000 outputs. To ensure the CW33000 timing given earlier in this chapter, the customer design must not present loading in excess of the values provided in the table.

The customer loading numbers make the following assumptions. Note that the values for wire and fan-out capacitance are process-specific, so the calculations must be repeated if a different process is used.

1. Process: For the LSI Logic LCB007 process, the unit wire capacitance is 0.1702 pF/ and one standard load is 0.0784 pF.

2. Data Cache: The data cache, if used, must be positioned such that the interconnect length does not exceed 7 mm, and the data cache signals support no other interconnect.
   - Wire contribution per signal = 7 mm x (0.1702 pF/mm) = 1.2 pF
   - Fan-out contribution = 0.3 pF for RAM
   - Total load for each data cache signal = 1.2 + 0.3 = 1.5 pF

3. CPU Control Signals: For each CPU control signal, the customer peripheral logic presents a maximum of 15 mm of wire and a fan-out of 5.
   - Wire contribution per signal = 15 mm x (0.1702 pF/mm) = 2.6 pF
   - Fan-out contribution = 5 std. lds. x 0.0784 pF/std. ld. = 0.3 pF
   - Total load for each CPU control signal = 2.9 pF = 3 pF (rounded)

4. Control Signals: For each control signal, the customer peripheral logic presents a maximum of 20 mm of wire and a fan-out of 5.
   - Wire contribution per signal = 20 mm x (0.1702 pF/mm) = 3.4 pF
   - Fan-out contribution = 5 std. lds. x 0.0784 pF/std. ld. = 0.4 pF
   - Total load for each control signal = 3.8 pF

5. CDATAP Bus: Both the data cache and on-chip memory, if used, contribute to the loading on this bus.
   - Data cache wire contribution per signal (for 7 mm) = 1.2 pF
   - D-cache data input contribution per signal (1 std. ld.) = 0.08 pF
   - On-chip memory wire contribution per signal (for 7 mm) = 1.2 pF
   - On-chip memory input contribution per signal (1 std. ld.) = 0.08 pF
Total load for each CDATAP signal = 2.56 pF = 3 pF (rounded)

6. CDAP Bus: Assume 7 mm of wire and a fan-out of 4

- Wire contribution per signal = 7 mm x (0.1702 pF/mm) = 1.2 pF
- Fan-out contribution = 4 std. Ids. x 0.0784 pF/std. Id. = 0.3 pF
- Total load for each CDAP signal = 1.5 pF

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1. STALLN is a performance-critical signal; keep the external loading on STALLN as low as possible.
Appendix A
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